

# Consistent and protected End-to-End Data Aggregation Using Secret distribution in WSNs

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**Abstract-** Data aggregation in WSNs (Wireless sensor Networks) can effectively reduce communication overheads and therefore the energy consumption of detector nodes. A WSN must be not solely energy economical, however conjointly secure. Varied attacks could build data aggregation unsecure. We investigate the reliable and secure end to-end data aggregation downside considering selective forwarding attacks and modification attacks in homogenous cluster-based WSNs, and propose two data aggregation approaches. Our approaches, namely, Sign-Share and Sham-Share, use secret sharing and signatures to permit aggregators to combination the data while not understanding the contents of messages and therefore the base station to verify the collective data and retrieve the raw data from the collective data.

**Index Terms-** data aggregation, wireless sensor Networks, sign-shared and sham-share.

## I. INTRODUCTION

Data aggregation in WSNs (Wireless sensing element Networks) refers to the method of gathering and representing information in a very summary type. It will effectively scale back the info size, resulting in important energy reduction in transmittal and receiving data. Typically, a WSN is partitioned off into clusters with a cluster head in every cluster. Every cluster head gathers information from its members, aggregates the info, and sends the aggregate data to the bottom station. There square measure several security necessities for information aggregation, including information confidentiality, information integrity, information freshness, data convenience, authentication, and non-repudiation. The contents of the info in transit shouldn't be unconcealed to any party that's not licensed to own access. Data confidentiality is also achieved via 2 differing types of secure information aggregation

schemes, namely, end-to-end theme and hop-by-hop theme. Associate end-to-end theme doesn't use cryptography once aggregating the info, and therefore is more energy economical. Many end-to-end information aggregation schemes are projected. In a very hop-by-hop theme, a sensing element node encrypts its information and sends the encrypted information to its individual. Every individual, when cryptography, applies an aggregation perform to mixture the info, then encrypts it before causation it to a different individual or the bottom station. Since secret writing and cryptography square measure computationally expensive, a hop-by-hop theme might consume a big amount of energy and permit the individual to grasp secret contents. In WSNs, numerous attacks might exist. Among them square measure selective forwarding attacks and modification attacks. In the selective forwarding attacks, a malicious sensing element node might deliberately drop some packets received from alternative sensing element nodes, leading to packet loss. Within the modification attacks, a malicious sensing element node might modify some packets received from alternative sensing element nodes and forward the wrong packets to the base station. In this paper, we have a tendency to investigate the reliable and secure end-to end data aggregation drawback beneath each selective forwarding attack and modification attacks in homogeneous cluster-based WSNs. we have a tendency to create the subsequent major contributions:

- We have a tendency to propose 2 secure information aggregation approaches for the end-to-end information aggregation in WSNs supported secret sharing and signatures. The projected approaches can defend against each selective forwarding attacks and modification attacks. To the simplest of our information, our approaches square

measure the primary one considering each the selective forwarding attacks and also the modification attacks and providing secure end-to-end information aggregation in homogeneous cluster-based WSNs while not encrypting messages.

- We've compared each approach and 2 state-of-the-art approaches, specifically PIP and RCDA-HOMO, using intensive simulations. The simulation results show that our approaches take less time in process the info and aggregating the info.

## II. PRAPOSED ALGORITHM

**SIGN-SHARE:**-In our Sign-Share approach, each sensor node splits its data into multiple shares and sends some of them to the aggregators of its cluster, allowing encoding each share with simpler codes. For ease of description, we assume that the data sensed by each sensor each time is 32-bits long, and the 32-bit data is split into four 8-bit shares. Our Sign-Share approach consists of the following phases:

Setup Phase:

The following system parameters are generated and loaded into each sensor node at the design stage.

- A secret key-set K in a form of matrix shown as follows:

$$K = \begin{bmatrix} \lambda_0 & \mu_0 \\ \lambda_1 & \mu_1 \\ \lambda_2 & \mu_2 \\ \lambda_3 & \mu_3 \end{bmatrix} \quad 0 \leq \lambda_k, \mu_k < P$$

The larger the P, the more secure the aggregations.

- A secret 32-bit pseudo random binary sequence generator P RBSp[I, n], where I is the seed and n is the clock.
- (p<sub>vi</sub>, pr<sub>vi</sub>): this pair is generated according to the algorithm proposed by Boneh et al. [13]. However, the private key pr<sub>vi</sub> is set to λ<sub>0</sub>.
  - P<sub>vi</sub>: the public key which is kept at the base station.
  - Pr<sub>vi</sub>: the private key which is loaded to each sensor node v<sub>i</sub>.
- A hash function H for all the sensor nodes.

Secret Sharing-Signature Phase:-

When a sensor node v<sub>i</sub> senses the physical environment and prepares its data D to be sent to its aggregators, it does the following:

- Each sensor v<sub>i</sub> splits its data as follows:
  - 1) Encode the data: D<sub>0</sub> = D ⊕ P RBSp [I, n], where ⊕ is the bitwise XOR.
  - 2) Split the encoded data into 4 shares B<sub>0</sub>, B<sub>1</sub>, B<sub>2</sub>, and B<sub>3</sub>.
  - 3) Encode each byte B<sub>k</sub> using the key-set K as follows:

$$B'_k = ((B_k * \lambda_k) + \mu_k) \text{ mod } 256 \quad (1)$$

- Sign each byte as follows:

$$h_i = H(B'_k) \quad (2)$$

$$\sigma_i = pr_{v_i} * h_i \quad (3)$$

- Send the data in a tuple (B<sub>0</sub> k, σ<sub>i</sub>) to each aggregator of its cluster such that the data after encoding is split equally between them

## III. AGGREGATION PHASE

When an aggregator node receives the tuple from every member of its cluster, it does the following:

Let (B'<sub>0</sub>, σ<sub>0</sub>), (B'<sub>1</sub>, σ<sub>1</sub>), ..., (B'<sub>w-1</sub>, σ<sub>w-1</sub>) be all the tuples received.

Aggregate the signatures as follows:

$$\hat{\sigma} = \sum_{i=1}^w \sigma_i$$

- Aggregate all the shares as follows:

- Concatenate the w bytes into a single value Q as follows:

$$Q = B'_0 | B'_1 | \dots | B'_{w-1} \quad (5)$$

- Send the concatenated data in a tuple (Q, σ̂) to the base station.

Verification-Decoding Phase:-

When the base station receives the data from every aggregator AG<sub>i</sub>, it does the following:

- Let w be the number of shares received from AG<sub>i</sub>.
- Extract the Q bytes of each tuple received from AG<sub>i</sub>.
- Recover the 32-bit data of each node v<sub>i</sub> as follows:
  - 1) Decode each byte using the key-set K of v<sub>i</sub>:

$$B_k = ((B'_k - \mu_k) * \lambda_k^{-1}) \text{ mod } 256 \quad (6)$$

2) Merge the decoded bytes into one 32-bit integer D0.

3) Decipher the data:  $D = D0 \oplus \text{PRBSp}[L, n]$ .

• Verify D by using Boneh et al. algorithm.

SHAM-SHARE:-

Our Sham-Share approach consists of the following phases:

Setup Phase: The base station generates the following key pair (puvi , prvi ) for each sensor node vi as in, where puvi is the public key kept in the base station, and prvi is the private key loaded to each sensor node vi along with H, the hash function for all the sensor nodes

Secret Sharing-Signature Phase: When a sensor node vi senses the physical environment and prepares its data S to be sent to its aggregators, it performs the following tasks:

• The sensor node vi splits the data S into 4 shares as follows:

1) Generate two random numbers a0, a1.

2) Construct the following polynomial function:

$$f(x) = S + a_0x + a_1x^2 \quad (7)$$

3) Construct 4 shares with each share represented by a pair (x, f(x))(x = 1, 2, 3, 4). Shares start from (1, f(1)) because f(0) is the data S.

4) Let IDi be the ID of the sensor node vi . Encode each share of vi as follows:

$$Q_i = x + 10ID_i + 1000f(x) \quad (8)$$

• Sign each share as follows:

$$h_i = H(Q_i) \quad (9)$$

$$\sigma_i = pr_{vi} * h_i \quad (10)$$

Send the tuples (Q1, σ1), (Q2, σ2) to one aggregator, and (Q3, σ3), (Q4, σ4) to the other aggregator

Aggregation Phase: After an aggregator AGi receives the tuple from every member of its cluster, it performs the following tasks:

• The aggregator gathers all the w tuples (Q0, σ0), (Q1, σ1), ..., (Qw-1, σw-1) from the members of its cluster.

• Aggregate the signatures as follows:

$$\hat{\sigma} = \sum_{i=1}^w \sigma_i \quad (11)$$

• Send the data in an array which contains the aggregated signature and the aggregated shares.

$$\begin{bmatrix} \hat{\sigma} \\ Q_0 \\ Q_1 \\ \dots \\ Q_{w-1} \end{bmatrix}$$

Reconstruction-Verification Phase: After the base station receives the data from all the aggregators, it performs the following tasks for each aggregator AGi:

• Let w be the number of shares received from AGi.  
• Disaggregate Qi of each array received from AGi as follows:

$$\begin{bmatrix} f(x_0), ID_0, x_0 \\ f(x_1), ID_1, x_1 \\ \dots \\ f(x_{w-1}), ID_k, x_{w-1} \end{bmatrix} =$$

$$\begin{bmatrix} [Q_0/1000], [Q_0/10] \text{ mod } 100, Q_0 \text{ mod } 10 \\ [Q_1/1000], [Q_1/10] \text{ mod } 100, Q_1 \text{ mod } 10 \\ \dots \\ [Q_{w-1}/1000], [Q_{w-1}/10] \text{ mod } 100, Q_{w-1} \text{ mod } 10 \end{bmatrix}$$

• Gather 3 shares of each sensor node vi , and reconstruct its data S as follows:

$$S = \sum_{j=0}^2 f(x_j) \prod_{m=0, m \neq j}^2 \frac{x_m}{x_m - x_j} \quad (12)$$

Verify S by using Boneh et al. algorithm.

#### IV. CONCLUSION

We have planned 2 reliable and secure end-to-end information aggregation approaches that not exclusively conceal the detected data but in addition allow the bottom station to sight every the selective forwarding attacks and conjointly the modification attacks. The proposed ways perform higher

performance than existing PIP and RCDA-HOMO in terms of the aggregation interval and conjointly the device interval, which they considerably perform beyond PIP in terms of the network time period, the network delay, and also the aggregation energy consumption.

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