

On Decompositions of Continuity in Topological Spaces

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Abstract- In this paper, we obtain two decompositions of continuity via strong semi closed sets in topological spaces.

Index Terms- Decomposition, strong semi closed set.

I. INTRODUCTION AND PRELIMINARIES

A subset S of a topological space is said to be regular open in X if $S = \text{int}(\text{cl}(S))$

1.1. Definition

A subset S of X is called

- Strong semiclosed set in X if $S = A \cap F$, where A is regular open and F is closed in X ,
- Generalized closed (g -closed), if $\text{cl}(S) \subseteq G$ whenever $S \subseteq G$ whenever $S \subseteq G$ and G is regular open in X ,
- Generalized continuous (g -continuous) if $f^{-1}(F)$ is g -closed in X for each closed set F in Y .

1.2. Definition

A map $f: X \rightarrow Y$ is called

- generalized continuous (g -continuous) if $f^{-1}(F)$ is g -closed in X for each closed set F in Y ,
- regular generalized continuous (rg -continuous) if $f^{-1}(F)$ is rg -closed in X for each closed set F in Y ,
- Strong semicontinuous if $f^{-1}(F)$ is strong semiclosed in X for each closed set F in Y .

II. DECOMPOSITION

Two decompositions of continuous maps, two decompositions of closed maps and two decompositions of contra continuous maps in topological spaces are obtained in this section. Further, we consider Baker's [1] decomposition of continuity for a brief study.

2.1. Theorem

A subset S is closed in X if and only if it is both g -closed and strong semi closed in X .

Proof:

Necessity is trivial. We prove the sufficiency. Let S be both g -closed and strong semi-closed in X . Since, S is strong semi-closed in X , $S = A \cap F$, where A is regular open and F is closed in X . So, $S \subseteq A$ and $S \subseteq F$. Since S is g -closed, $\text{cl}(S) \subseteq A$. Also, we have, $\text{cl}(S) \subseteq \text{cl}(F) = F$. This implies, $\text{cl}(S) \subseteq A \cap F = S$. Hence $\text{cl}(S) = S$. Therefore S is closed.

2.2. A Theorem

subset S is closed in X if and only if it is both rg -closed and strong semi closed in X .

Proof:

Necessity is trivial. We prove the sufficiency. Let S be both rg -closed and strong semi closed in X . Since, S is strong semi closed in X , $S = A \cap F$, where A is regular open and F is closed in X . So, $S \subseteq A$ and $S \subseteq F$. Since S is rg -closed, $\text{cl}(S) \subseteq A$. Also, we have, $\text{cl}(S) \subseteq \text{cl}(F) = F$. This implies, $\text{cl}(S) \subseteq A \cap F = S$. Hence $\text{cl}(S) = S$. Therefore S is closed.

2.3. Corollary

The following are equivalent for a map $f: X \rightarrow Y$:

- f is continuous,
- f is g -continuous and strong semi continuous,
- f is rg -continuous and strong semi continuous.

Proof:

The proof follows from Theorem 2.1. and Theorem 2.2.

2.4. Definition

A map $f: X \rightarrow Y$ is said to be a strong semi closed map if $f(F)$ is strong semi closed in Y for each closed set F in X .

2.5. Corollary

The following are equivalent for a map $f: X \rightarrow Y$:

- f is closed,
- f is g -closed and strong semi closed,
- f is rg -closed and strong semi closed.

Proof:

Follows from Theorem 2.1. and Theorem 2.2.

2.6. Corollary

The following are equivalent for a map $f: X \rightarrow Y$:

1. f is contra continuous,
2. f is contrag-continuous and contra strong semi continuous,
3. f is contrarg-continuous and contra strong semi continuous.

Proof:

Follows from Theorem 2.1. and Theorem 2.2.

Baker[1] obtained a decomposition of continuity: A map $f: X \rightarrow Y$ is continuous if and only if, for each open set V in Y , $f^{-1}(V) \subseteq \text{int}(\text{cl}(f^{-1}(\text{cl}(V))))$ and $f^{-1}(V)$ is open in the subspace $\text{cl}(f^{-1}(\text{cl}(V)))$.

For brevity, a map $f: X \rightarrow Y$ is called B_1 -continuous if $f^{-1}(V) \subseteq \text{int}(\text{cl}(f^{-1}(\text{cl}(V))))$ for each open set V in Y and a map $f: X \rightarrow Y$ is called B_2 -continuous if $f^{-1}(V)$ is open in the subspace $\text{cl}(f^{-1}(\text{cl}(V)))$ for each open set V in Y , in the present study.

Example 2.7.

Let $X = \{a, b, c\}$ and $\square = \{\square, \{a\}, X\}$. Define $f: (X, \square) \rightarrow (X, \square)$ by $f(a) = f(b) = a$ and $f(c) = c$. Then f is B_1 -continuous, g -continuous and rg -continuous but is neither B_2 -continuous nor strong semi continuous.

Example 2.8.

Let $X = \{a, b, c\}$ and $\tau = \{\square, \{a\}, \{b\}, \{a, b\}, X\}$. Define $f: (X, \square) \rightarrow (X, \square)$ by $f(b) = f(c) = a$ and $f(a) = c$. Then f is B_1 -continuous, strong semi continuous but is neither B_2 -continuous nor g -continuous nor rg -continuous.

Example 2.9.

Let $X = \{a, b, c, d, e\}$, $Y = \{x, y, z\}$, $\tau = \{\square, \{a\}, \{b\}, \{a, b\}, X\}$ and $\square = \{\square, \{x\}, \{y, z\}, Y\}$. Define $f: (X, \tau) \rightarrow (Y, \square)$ by $f(a) = f(b) = f(c) = x$, $f(d) = y$ and $f(e) = z$. Then f is g -continuous and rg -continuous but not B_1 -continuous.

Example 2.10.

Let $X = \{a, b, c, d\}$, $Y = \{x, y, z\}$, $\tau = \{\square, \{c\}, \{d\}, \{c, d\}, \{a, c\}, \{a, c, d\}, X\}$ and $\sigma = \{\square, \{z\}, \{x, y\}, Y\}$. Define $f: (X, \tau) \rightarrow (Y, \sigma)$ by $f(a) = f(b) = f(c) = x$ and $f(d) = z$. Then f is strong semi continuous and B_2 -continuous but is neither g -continuous nor rg -continuous nor B_1 -continuous.

Example 2.11.

Let (X, τ) and (Y, \square) be as in Example 2.10. Define $f: (X, \tau) \rightarrow (Y, \square)$ by $f(a) = f(b) = x$, $f(c) = z$ and $f(d) = y$. Then f is B_2 -continuous but not strong semi continuous.

III. REMARK

In this remark, we sum up the results.

- (a) The decomposition of continuity into semi continuity and $D(c, s)$ -continuity obtained in [2] is the same as the decomposition of continuity obtained by Ganster and Reilly [3], because the notion of semi continuity coincides with the notion of quasi continuity [4] and the notion of $D(c, s)$ -continuity coincides with the notion of ic -continuity.
- (b) The decompositions of continuity obtained in Corollary 2.3 are different from other decompositions of continuity considered in this paper.
- (c) The decompositions of continuity obtained in Corollary 2.3 are independent of other decompositions of continuity considered, including Levine's and Baker's, except those involving semi continuity and \square -continuity.
- (d) The second decomposition obtained, is an improvement over the first.

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