

Study of Switched Boost Inverter Methods

Shaikh Sufiyan Ahmed¹, S.S. Kamble²

¹M.tech (EPS), Electrical Engineering Department, P.E.S College of Engineering Aurangabad, (MS) India

²Associate Professor & PG Dean, Electrical Engineering Department, P.E.S College of Engineering Aurangabad, (MS) India

Abstract- This work proposes the Switched Boost Inverter (SBI), a single stage buck boost DC-AC inverter. This essay's goal is to examine the SBI's operating theory and analysis, as well as open-loop and closed-loop simulation. This innovative power converter is a descendant of the Z Source Inverter (ZSI), which demonstrates all of its benefits while using fewer passive components. With the aid of an impedance network, ZSI has the unique ability to function in buck or boost mode. This enables the input voltage to be increased by shooting through the inverter legs' switching state. The shoot through interval was incorporated into each switching cycle using modified Pulse Width Modulation (PWM) techniques. The output voltage of the inverter's harmonic spectrum is also displayed. Using fuzzy and proportional integral (PI) controllers, the circuit was closed-loop controlled. This PI-Fuzzy controller makes designing controllers simpler and boosts system reliability. The proposed technique was validated by simulated studies using MATLAB and Simulink. Simulation results demonstrate the benefits of the suggested approach. Despite the fact that ZSI has several advantages over VSI/CSI, the size of the impedance network components is a major cause for concern because it increases ZSI's size, weight, and cost. All of the benefits of the conventional impedance source inverter (ZSI) topology are present in the switching boost inverter design, but there are more active components needed and the number of passive components is reduced. MATLAB software is used to simulate and mathematically analyse the switching boost inverter structure, and results are generated. The SBI topology is controlled during simulation using two different forms of PWM control approaches.

Keywords: Z source inverter; switched boost inverter; PWM; buck inverter; boost factor

1. INTRODUCTION.

A system or device that can continually regulate power output is known as an electronic regulator. A linear regulator has a poorer efficiency and uses more energy in the form of heat since it regulates the output using a resistive voltage drop. In contrast, a switching regulator uses an inductor, a diode, and a power switch to move energy from its source to its output.

The three types of switching regulators available.

1. Step-up converter (Boost Regulator)

Any DC to DC converter with an output voltage higher than the source voltage is referred to as a boost converter. Since a boost converter "steps up" the source voltage, it is sometimes referred to as a step-up converter. The output current is less than the source current because power () must be conserved.

2. Step-Down converter (Buck regulator)

There in case of buck converters, the constant dc input voltage is transformed into a different, lower value, dc signal at the output. This shows that it is designed to have a dc output signal whose magnitude is less than the applied input. It is also known as a Buck Regulator, Step-down DC to DC Converter, and Step-down Chopper.

3. Inverter (Flyback)

Power converters that convert AC to DC with galvanic isolation between the inputs and outputs are known as flyback converters. When there is current going through the circuit, it stores energy; when the power is turned off, it releases energy. It functions as an isolated switching converter for step down or step up voltage transformers and utilised a mutually connected inductor. With a wide range of input voltages, it can regulate and control numerous output voltages. When compared to other switching mode power supply circuits, the number of components needed to create a flyback converter is minimal. The on/off switch action utilised in the design is referred to as "flyback"

A contrast between a two-level DC/DC boost inverter and a quasi-switched boost inverter (qSBI) for photovoltaic applications. Based on operating mode, steady-state operation, boost factor, voltage gain, and power loss, these two inverter topologies are contrasted. For the purpose of validating the theoretical idea, both topologies are simulated in the MATLAB/SIMULINK environment using an input DC voltage of 36 V, a modulation index of 0.5, and a shoot-through duty cycle of 0.45. The two topologies' harmonic profiles are shown. To support the simulation, experimental findings are presented.

A thorough investigation reveals that the embedded qSBI (EqSBI), one of the single-level qSBI topologies, has advantages over the conventional DC/DC boost inverter design.

To decrease switching losses in high frequency converters, numerous lossless passive soft-switching techniques have been put forth in the literature (some examples are given in [1]–[4]). For smooth on/off switching, use diodes, capacitors, and resonant coils. These components are intrinsically more reliable since they fail less frequently than active elements (i.e., metal oxide semiconductor field effect transistors, or MOSFETS) used in techniques.

The efficiencies of active and passive soft change ways for PWM converters. The losses in each ways were in theory itemized and by experimentation measured. The values of the resonant parts were by experimentation optimized in order that each ways were compared on their best conditions. a lift device was designed and tested beneath the static and dynamic greenhouse emission operation condition similarly as DC-DC operation condition. Studies show that the passive methodology has higher potency within the high power operation region, whereas the active methodology outperforms the passive methodology within the low power region.

2. COMPARATIVE BENEFITS OF SWITCHING BOOST INVERTER METHOD OVER OTHER BOOST METHODS

2.1 Design Basics of Boost Converter Circuit

In several cases, we'd like to convert lower voltage to the upper voltage counting on the necessities. The voltage is raised from a lower potential to a greater potential using a boost regulator.

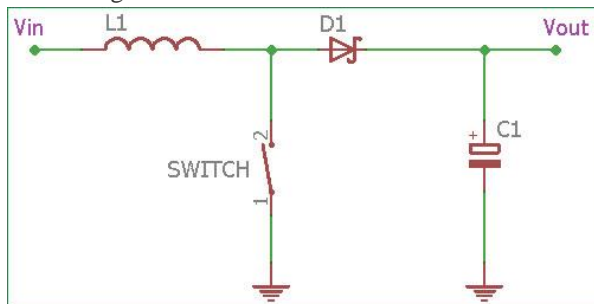


Figure. 1(a)

Also, the inductor stores energy, the energy measured in Joules $E = (L * I^2 / 2)$ We will understand how the inductors transfer energy in the upcoming Figure. 1(a), 1(b) and graphs figure 3. There are two phases in switching boost regulators: the inductor charge phase, also known as the switch on phase (the switch is actually closed), and the discharge phase, often known as the switch off phase (Switch is open).

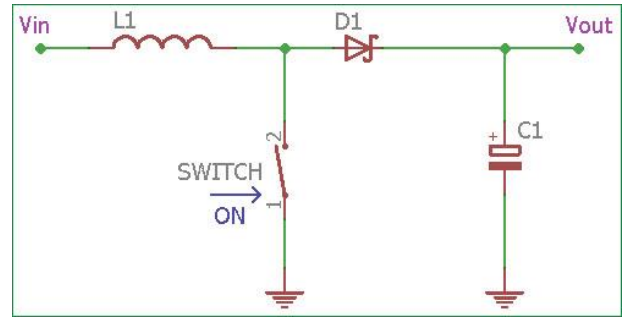


Figure. 1(b)

If we assume that the switch has been in the open position for a considerable amount of time, the voltage drop across the capacitor is equal to the input voltage, and the voltage drop across the diode is negative. In this case, the V_{in} is scared across the inductor if the switch approaches. The diode stops the capacitor from discharging to ground by passing through the switch. The current through the inductor rises at linearly with time. The input voltage divided by the inductance determines how quickly the linear current rises ($di/dt = \text{voltage across inductor} / \text{inductance}$).

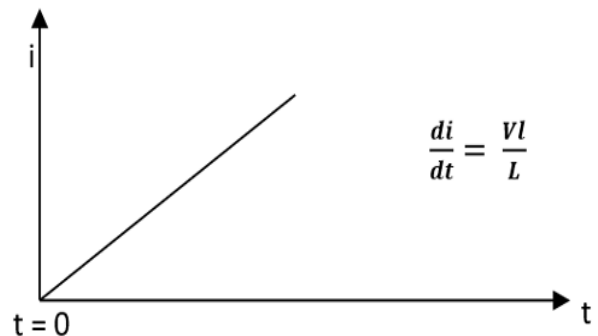


Figure. 3

In the Figure. 3 graph, Charging phase of the inductor. The x-axis t (time) and the Y-axis I (current through the inductor). When the switch is closed or ON, the Current grows linearly over time.

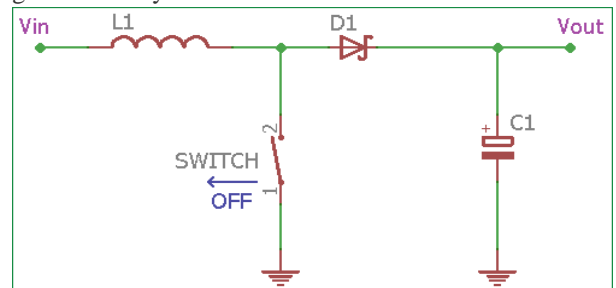


Figure. 4

Now, the inductor current flows through the diode and charges the output capacitor when the switch is turned back on or becomes open. The current slope through the inductor reverses as the output voltage increases. Up until Voltage through the inductor $= L * (di / dt)$ is obtained, the output voltage increases. The inductor voltage has a direct relationship with the pace at which the inductor current decreases over time. The current

drop through the inductor is accelerated by an increase in inductor voltage.

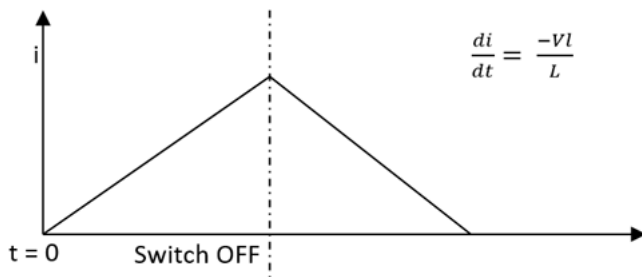


Figure. 5

In the Figure. 5 graph, the inductor current drops with time when the switch becomes off. When the switching regulator is working under steady-state conditions, the average voltage of the inductor is zero throughout the switching cycle. The average current flowing through the inductor under these circumstances is also steady-state. There will be a particular T_{off} or discharge time for an output voltage if the inductor charging time is assumed to be T_{on} and the circuit has an input voltage.

2.2 PWM and Duty Cycle for Boost Converter Circuit

The boost converter's steady-state output can be controlled by adjusting the duty cycle. Therefore, we employ a control circuit across the switch to adjust the duty cycle.

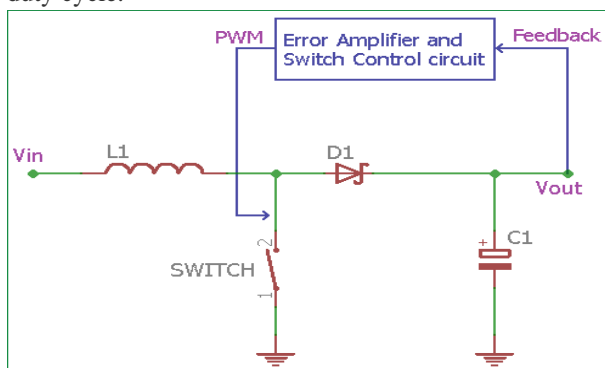


Figure. 6

Consequently, we require extra circuitry to alter the duty cycle, and thereby the duration of time the inductor receives energy from the source, in order to create a complete basic boost regulator circuit. An error amplifier that senses the output voltage across the load via a feedback route and controls the switch may be seen in the Figure. 6. The most widely used control technique is PWM, or pulse width modulation, which regulates the duty cycle of the circuitry.

The error voltage is also impacted by variations in the output voltage. The comparator regulates the PWM output as a result of an erroneous voltage change. The closed control loop system is used to carry out the work by changing the PWM to a position where the output voltage produces zero error voltage. Fortunately, this

feature is included into the majority of contemporary switching boost regulators. Thus, utilising the current switching regulators, simple circuitry design is accomplished. A resistor divider network is used to create the reference feedback voltage. This is the extra wiring that is required in addition to the inductor, diodes, and capacitors.

2.3 SBI is a single-stage power converter

That can concurrently power ac loads between nodes AO and BO and dc loads between nodes VDC and ground from a single dc input. As a result, it is capable of achieving both a solar panel dc-to-dc converter and a dc-to-ac converter in a single stage. This reduces the size and expense of the entire system.

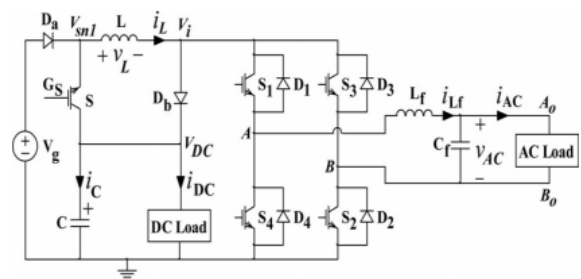


Figure.7

Figure.7 shows the SBI circuit diagram for powering both dc and ac loads. SBI's output ac voltage can differ from the available source voltage in either direction. As a result, it can produce a wide range of output voltages from a given source voltage. When compared to a conventional voltage source inverter (VSI), the SBI exhibits better immunity to electromagnetic interference (EMI) noise because the shoot-through, which occurs when both switches in one leg of the inverter bridge are turned ON simultaneously, does not harm the inverter switches [4].

3. COMPARISON OF SBI WITH A TRADITIONAL TWO-STAGE DC-TO-AC CONVERSION SYSTEM

The SBI is a single-input, two-output (one dc output and one ac output) power converter that is generated from an IWJ converter and a VSI, as was demonstrated in the preceding section. The SBI can also provide an ac output voltage that is either more or less than the input dc voltage, just like the conventional two-stage dc-to-ac conversion system.

1) **Dead-Time Requirement:** A shoot-through event in the inverter bridge damages the power converter stage of the two-stage conversion system as well as the dc loads connected to the nanogrid's dc bus. But this is not the case because SBI permits shoot-through in the inverter

phase legs. A deadtime circuit and dead-time compensation techniques are no longer necessary when using SBI.

2) Reliability and EMI Noise Immunity: Because an EMI noise can potentially produce shoot-through in the inverter phase legs, the likelihood of an event occurring even with a deadtime circuit cannot be totally reduced [4], [7]. The switches of the power converter are not harmed by the shoot-through event when SBI is used. In comparison to the two-stage conversion system, SBI has better EMI noise protection and is hence more reliable.

3) Extreme duty cycle operation: The inductor L is charged over a longer period of time during the switching cycle of a traditional boost converter when the duty ratio is operated at its maximum (for example, when $D = 0.75$), and only a very brief period of time is left to discharge the inductor through the output diode D_b . This diode should therefore be able to handle current with a relatively high amplitude and short pulsewidth. Additionally, this increases the EMI noise levels in the converter and generates severe diode reverse recovery current [11]–[14]. This also places a restriction on the boost converter's switching frequency, increasing the size of the passive parts utilised in the two-stage conversion system depicted in Fig 5. Figure 5 shows a conventional two-stage dc-to-ac converter. VSI and a boost converter in cascade.

4) Voltage Stress of Switching Devices: Fig. 8's two-stage conversion system and the semiconductor devices employed in the SBI's voltage stress are compared in Table I. From this table, it can be seen that in the case of SBI, the switch "S" experiences reduced voltage stress ($V_{DC} - V_g$). The voltage stress for all other devices is the same for the two-stage conversion system and SBI. Table 1 compares the voltage stresses of a two-stage conversion system with a sbi.

5) Maximum conversion ratio: Due to several non-idealities such as DCR/ESR of passive components, on-state voltage dips of semiconductor devices, etc., the highest conversion ratio (V_{DC}/V_g) of a realistic boost converter cannot exceed 3.0 (roughly). Depending on the actual values of nonideal elements included in the converter, this value may vary slightly. Similar to this, for a low distortion sine wave output, the rms ac output voltage (v_{AC} (rms)) of a singlephase inverter utilising sinusoidal PWM cannot exceed 2 times the dc link voltage (V_{DC}) [25], [27]. For a low distortion sine wave output, in the linear modulation range ($0-M-1$). Therefore, the two-stage conversion system's maximum overall rms ac-to-dc conversion ratio is around 2.12. If

the consequences of VSI's nonidealities are taken into account, this value could still fall.

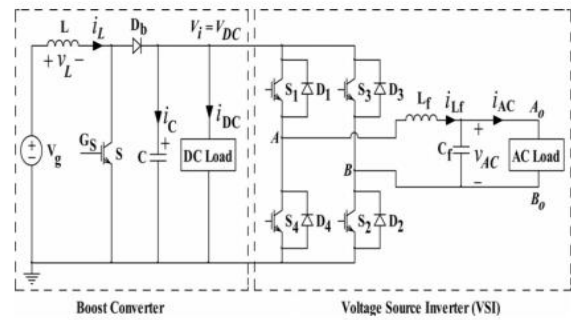


Figure.8

4. CONCLUSION.

For dc nanogrid applications, this project introduces a power electronic interface known as a switched boost inverter (SBI). It is demonstrated that the SBI is a single-stage power converter capable of simultaneously powering both dc and ac loads from a single dc input. The SBI's ability to produce an ac output voltage that is either higher or lower than the available source voltage has also been demonstrated. This essay also compares the ZSI and the conventional two-stage dc-to-ac conversion technology to the benefits and drawbacks of SBI. This work also describes a PWM control method appropriate for SBI as well as the steady-state and small-signal analysis of the SBI serving both dc and ac loads.

The ac output voltage of a switched boost inverter (SBI) can be either greater or lower than the dc input voltage. Additionally, compared to the VSI, this demonstrates greater EMI noise immunity, allowing for a more compact power converter design. It permits the shoot through switching state for increasing the input voltage, compensates for the dead time effect that seriously distorts the output voltage waveform, and reduces the possibility of harming the inverter switches. Future Aims Due to the system's ability to receive two separate outputs, it may operate multiple loads. Additionally, the DC output can be inverted and connected to an AC load. More details on the nano, micro, and smart grid were discussed.

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