

Modeling and analysis of Grid-Connected Multilevel PV Inverter with Distributed MPPT Techniques

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Abstract- This paper presents a modular cascaded H-bridge multilevel photovoltaic (PV) inverter for single- or three-phase grid-connected applications. The modular cascaded multilevel topology helps to improve the efficiency and flexibility of PV systems. To realize better utilization of PV modules and maximize the solar energy extraction, a distributed maximum power point tracking control scheme is applied to both single- and three-phase multilevel inverters, which allows independent control of each dc-link voltage. For three-phase grid-connected applications, PV mismatches may introduce unbalanced supplied power, leading to unbalanced grid current. To solve this issue, a control scheme with modulation compensation is also proposed. An experimental three-phase seven-level cascaded H-bridge inverter has been built utilizing nine H-bridge modules (three modules per phase). Each H-bridge module is connected to a 185-W solar panel. Simulation and experimental results are presented to verify the feasibility of the proposed approach.

Index terms- Cascaded multilevel inverter, distributed maximum power point (MPP) tracking (MPPT), modular, modulation compensation, photovoltaic (PV).

I. INTRODUCTION

Due to the shortage of fossil fuels and environmental problems caused by conventional power generation, renewable energy, particularly solar energy, has become very popular. Solar-electric-energy demand has grown consistently by 20%–25% per annum over the past 20 years [1], and the growth is mostly in grid-connected applications. With the extraordinary market growth in grid-connected photovoltaic (PV) systems, there are increasing interests in grid-connected PV configurations.

Five inverter families can be defined, which are related to different configurations of the PV system: 1) central inverters; 2) string inverters; 3) multistring inverters; 4) ac-module inverters; and 5) cascaded

inverters [2]–[7]. The configurations of PV systems are shown in Fig. 1.

Cascaded inverters consist of several converters connected in series; thus, the high power and/or high voltage from the combination of the multiple modules would favor this topology in medium and large grid-connected PV systems [8]–[10]. There are two types of cascaded inverters. Fig. 1(e) shows a cascaded dc/dc converter connection of PV modules [11], [12]. Each PV module has its own dc/dc converter, and the modules with their associated converters are still connected in series to create a high dc voltage, which is provided to a simplified dc/ac inverter. This approach combines aspects of string inverters and ac-module inverters and offers the advantages of individual module maximum power point (MPP) tracking (MPPT), but it is less costly and more efficient than ac-module inverters. However, there are two power conversion stages in this configuration. Another cascaded inverter is shown in Fig. 1(f), where each PV panel is connected to its own dc/ac inverter, and those inverters are then placed in series to reach a high-voltage level. This cascaded inverter would maintain the benefits of “one converter per panel,” such as better utilization per PV module, capability of mixing different sources, and redundancy of the system. In addition, this dc/ac cascaded inverter removes the need for the per-string dc bus and the central dc/ac inverter, which further improves the overall efficiency.

The modular cascaded H-bridge multilevel inverter, which requires an isolated dc source for each H-bridge, is one dc/ac cascaded inverter topology. The separate dc links in the multilevel inverter make independent voltage control possible. As a result, individual MPPT control in each PV module can be achieved, and the energy harvested from PV panels

can be maximized. Meanwhile, the modularity and low cost of

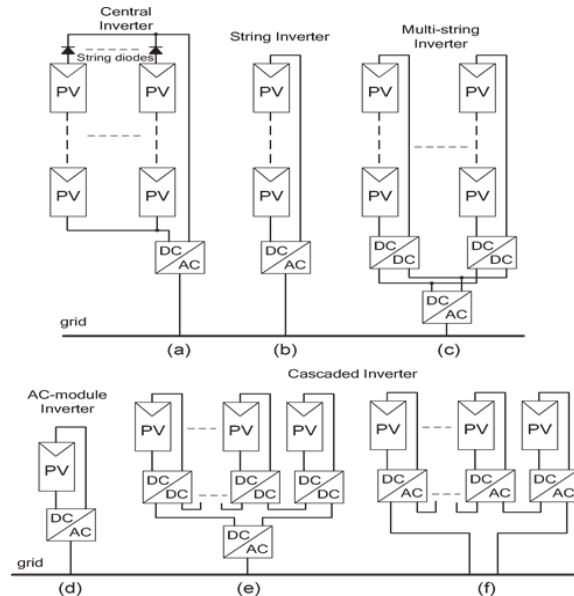


Fig. 1. Configurations of PV systems. (a) Central inverter. (b) String inverter. (c) Multistring inverter. (d) AC-module inverter. (e) Cascaded dc/dc converter. (f) Cascaded dc/ac inverter.

multilevel converters would position them as a prime candidate for the next generation of efficient, robust, and reliable grid-connected solar power electronics.

A modular cascaded H-bridge multilevel inverter topology for single- or three-phase grid-connected PV systems is presented in this paper. The panel mismatch issues are addressed to show the necessity of individual MPPT control, and a control scheme with distributed MPPT control is then proposed. The distributed MPPT control scheme can be applied to both single- and three-phase systems.

In addition, for the presented three-phase grid-connected PV system, if each PV module is operated at its own MPP, PV mismatches may introduce unbalanced power supplied to the three-phase multilevel inverter, leading to unbalanced injected grid current. To balance the three-phase grid current, modulation compensation is also added to the control system.

A three-phase modular cascaded multilevel inverter prototype has been built. Each H-bridge is connected to a 185-W solar panel. The modular design will increase the flexibility of the system and reduce the cost as well. Simulation and experimental

results are provided to demonstrate the developed control scheme.

II. SYSTEM DESCRIPTION

Modular cascaded H-bridge multilevel inverters for single- and three-phase grid-connected PV systems are shown in Fig. 2.

Each phase consists of n H-bridge converters connected in series, and the dc link of each H-bridge can be fed by a PV panel or a short string of PV panels. The cascaded multilevel inverter is connected to the grid through L filters, which are used to reduce the switching harmonics in the current.

By different combinations of the four switches in each H-bridge module, three output voltage levels can be generated: v_{dc} , 0, or $+v_{dc}$. A cascaded multilevel inverter with n input sources will provide $2n + 1$ levels to synthesize the ac output waveform. This $(2n + 1)$ -level voltage waveform enables the reduction of harmonics in the synthesized current, reducing the size of the needed output filters. Multilevel inverters also have other advantages such as reduced voltage stresses on the semiconductor switches and having higher efficiency when compared to other converter topologies [17].

III. PANEL MISMATCHES

PV mismatch is an important issue in the PV system. Due to the unequal received irradiance, different temperatures, and aging of the PV panels, the MPP of each PV module may be different. If each PV module is not controlled independently, the efficiency of the overall PV system will be decreased.

To show the necessity of individual MPPT control, a five-level two-H-bridge single-phase inverter is simulated in MATLAB/SIMULINK. Each H-bridge has its own 185-W PV panel connected as an isolated dc source. The PV panel is modeled according to the specification of the commercial PV panel from Astronergy CHSM-5612M.

Consider an operating condition that each panel has a different irradiation from the sun; panel 1 has irradiance $S = 1000 \text{ W/m}^2$, and panel 2 has $S = 600 \text{ W/m}^2$. If only panel 1 is tracked and its MPPT controller determines the average voltage of the two panels, the power extracted from panel 1 would be 133 W, and the power from panel 2 would be 70 W,

as can be seen in Fig. 3. Without individual MPPT control, the total power harvested from the PV system is 203 W.

However, Fig. 4 shows the MPPs of the PV panels under the different irradiance. The maximum output power values will be 185 and 108.5 W when the S values are 1000 and 600 W/m², respectively, which means that the total power harvested from the PV system would be 293.5 W if individual MPPT can be achieved. This higher value is about 1.45 times of the one before. Thus, individual MPPT control in each PV module is required to increase the efficiency of the PV system.

In a three-phase grid-connected PV system, a PV mismatch may cause more problems. Aside from

decreasing the overall efficiency, this could even introduce unbalanced power supplied to the three-phase grid-connected system. If there are PV mismatches between phases, the input power of each phase would be different. Since the grid voltage is balanced, this difference in input power will cause unbalanced current to the grid, which is not allowed by grid standards. For example, to unbalance the current per phase more than 10% is not allowed for some utilities, where the percentage imbalance is calculated by taking the maximum deviation from the average current and dividing it by the average current [18].

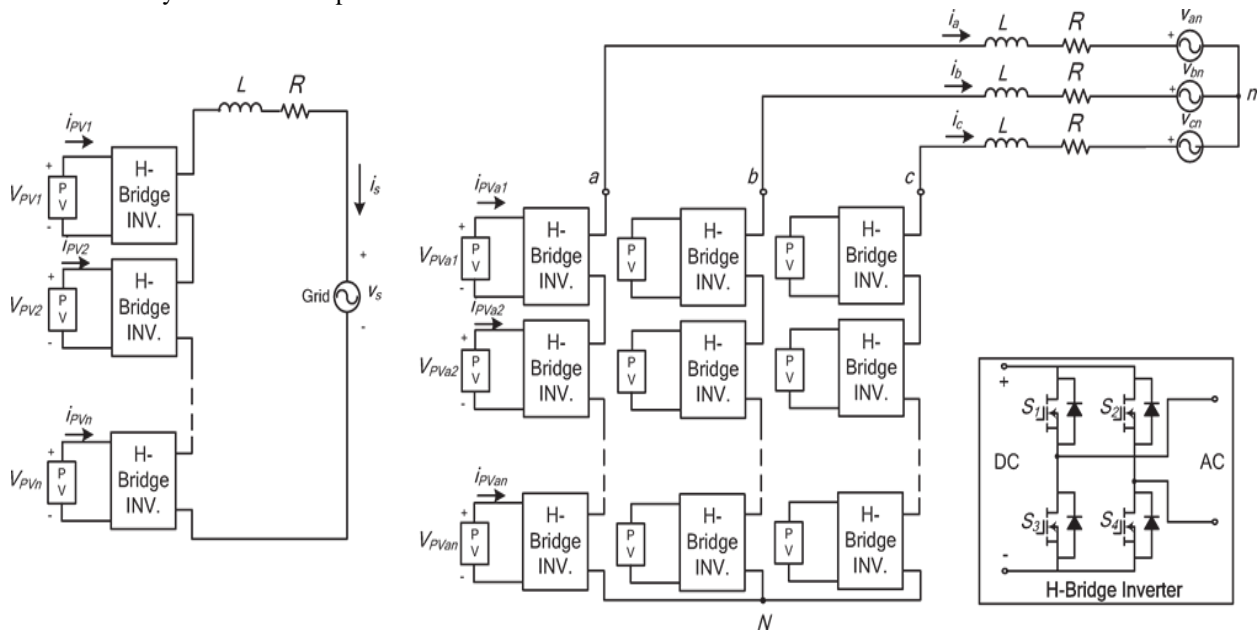


Fig. 2. Topology of the modular cascaded H-bridge multilevel inverter for grid-connected PV systems

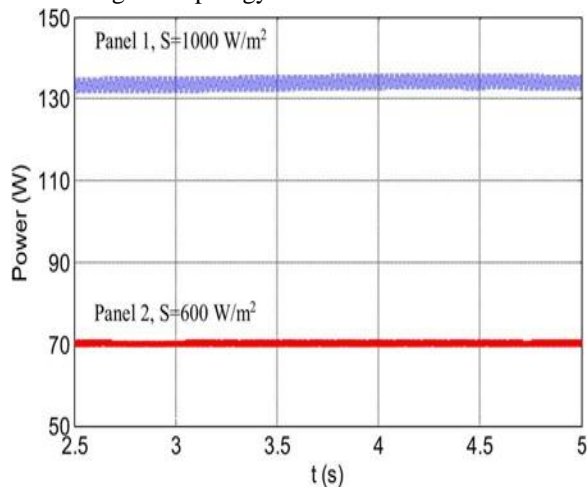


Fig. 3. Power extracted from two PV panels

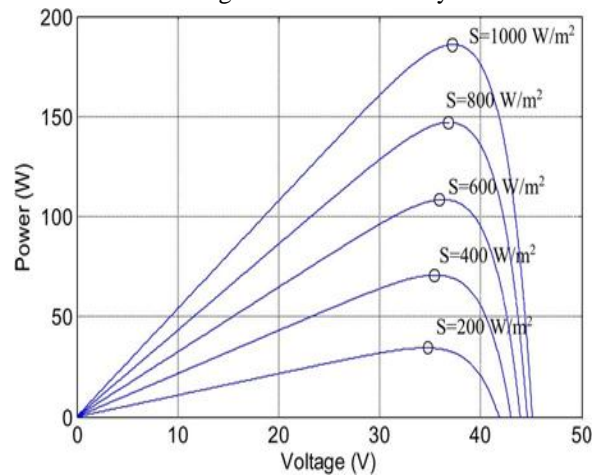


Fig. 4. P –V characteristic under the different irradiance

To solve the PV mismatch issue, a control scheme with individual MPPT control and modulation compensation is proposed. The details of the control scheme will be discussed in the next section.

IV. CONTROL SCHEME

A. Distributed MPPT Control

In order to eliminate the adverse effect of the mismatches and increase the efficiency of the PV system, the PV modules need to operate at different voltages to improve the utilization per PV module.

The separate dc links in the cascaded H-bridge multilevel inverter make independent voltage control possible. To realize individual MPPT control in each PV module, the control scheme proposed in [19] is updated for this application.

The distributed MPPT control of the three-phase cascaded H-bridge inverter is shown in Fig. 5. In each H-bridge module, an MPPT controller is added to generate the dc-link voltage reference. Each dc-link voltage is compared to the corresponding voltage reference, and the sum of all errors is controlled through a total voltage controller that determines the current reference I_{dref} . The reactive current reference I_{qref} can be set to zero, or if reactive power compensation is required, I_{qref} can also be given by a reactive current calculator [20], [21]. The synchronous reference frame phase-locked loop

(PLL) has been used to find the phase angle of the grid voltage [22]. As the classic control scheme in three-phase systems, the grid currents in abc coordinates are converted to dq coordinates and regulated through proportional-integral (PI) controllers to generate the modulation index in the dq coordinates, which is then converted back to three phases.

The distributed MPPT control scheme for the single-phase system is nearly the same. The total voltage controller gives the magnitude of the active current reference, and a PLL provides the frequency and phase angle of the active current reference. The current loop then gives the modulation index.

To make each PV module operate at its own MPP, take phase *a* as an example; the voltages v_{dca2} to $v_{dca n}$ are controlled individually through $n-1$ loops. Each voltage controller gives the modulation index proportion of one H-bridge module in phase *a*. After multiplied by the modulation index of phase *a*, $n-1$ modulation indices can be obtained. Also, the modulation index for the first H-bridge can be obtained by subtraction. The control schemes in phases *b* and *c* are almost the same. The only difference is that all dc-link voltages are regulated through PI controllers, and n modulation index proportions are obtained for each phase.

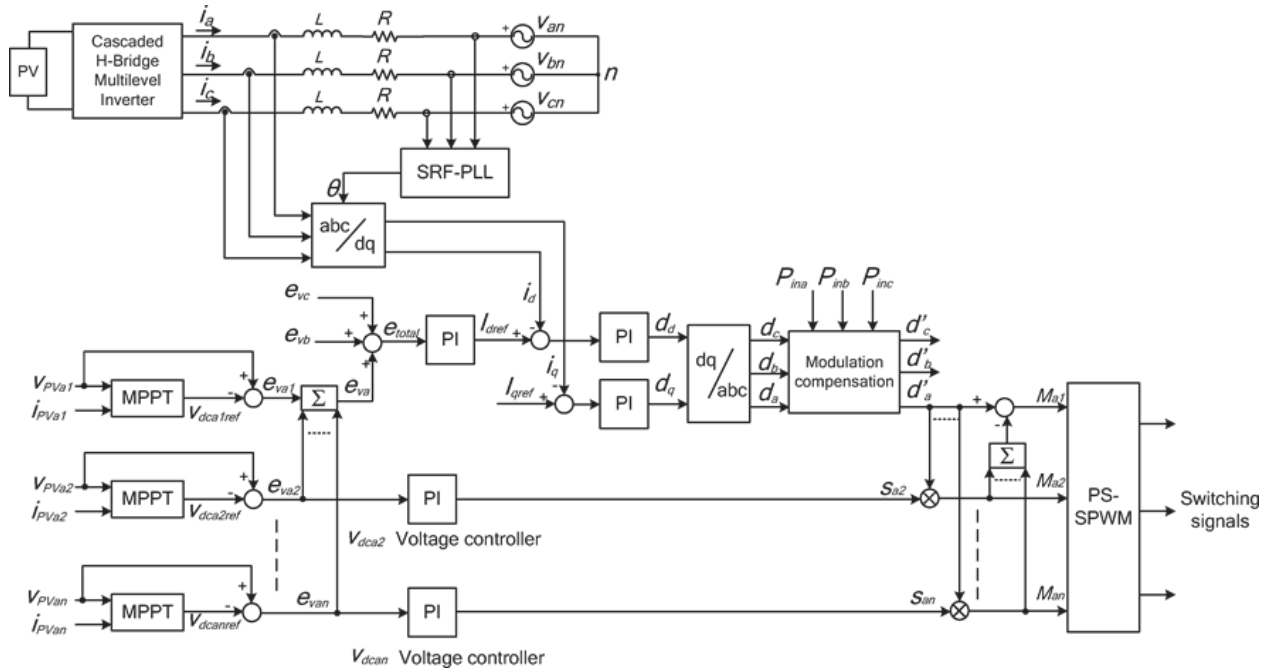


Fig. 5. Control scheme for three-phase modular cascaded H-bridge multilevel PV inverter

A phase-shifted sinusoidal pulse width modulation switching scheme is then applied to control the switching devices of each H-bridge.

It can be seen that there is one H-bridge module out of N modules whose modulation index is obtained by subtraction. For single-phase systems, $N = n$, and for three-phase systems, $N = 3n$, where n is the number of H-bridge modules per phase. The reason is that N voltage loops are necessary to manage different voltage levels on N H-bridges, and one is the total voltage loop, which gives the current reference. So, only $N-1$ modulation indices can be determined by the last $N-1$ voltage loops, and one modulation index has to be obtained by subtraction. Many MPPT methods have been developed and implemented. Many MPPT methods have been developed and implemented [23], [24]. The incremental conductance method has been used in this paper. It lends itself well to digital control, which can easily keep track of previous values of voltage and current and make all decisions.

B. Modulation Compensation

As mentioned earlier, a PV mismatch may cause more problems to a three-phase modular cascaded H-bridge multi-level PV inverter. With the individual MPPT control in each H-bridge module, the input solar power of each phase would be different, which introduces unbalanced current to the grid. To solve the issue, a zero sequence voltage can be imposed upon the phase legs in order to affect the current flowing into each phase [25], [26]. If the updated inverter output phase voltage is proportional to the unbalanced power, the current will be balanced.

Thus, the modulation compensation block, as shown in Fig. 6, is added to the control system of three-phase modular cascaded multilevel PV inverters. The key is how to update the modulation index of each phase without increasing the

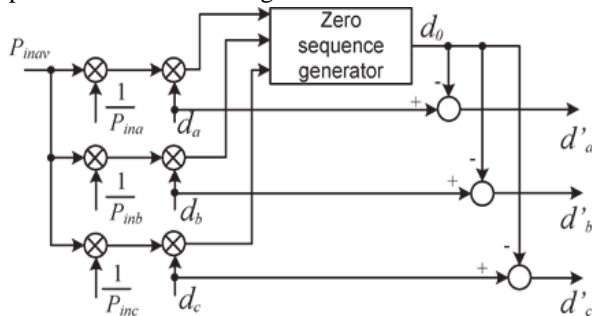


Fig. 6. Modulation compensation scheme

complexity of the control system. First, the unbalanced power is weighted by ratio r_j , which is calculated as

$$r_j = \frac{P_{inav}}{P_{inj}} \tag{1}$$

Where P_{inj} is the input power of phase j ($j = a, b, c$), and P_{inav} is the average input power.

Then, the injected zero sequence modulation index can be generated as

$$d_0 = \frac{1}{2} [\min(r_a \cdot d_a, r_b \cdot d_b, r_c \cdot d_c) + \max(r_a \cdot d_a, r_b \cdot d_b, r_c \cdot d_c)] \tag{2}$$

where d_j is the modulation index of phase j ($j = a, b, c$) and is determined by the current loop controller.

The modulation index of each phase is updated by

$$d'_j = d_j - d_0. \tag{3}$$

Only simple calculations are needed in the scheme, which will not increase the complexity of the control system. An example is presented to show the modulation compensation scheme more clearly. Assume that the input power of each phase is unequal $P_{ina} = 0.8$ $P_{inb} = 1$ $P_{inc} = 1$. (4)

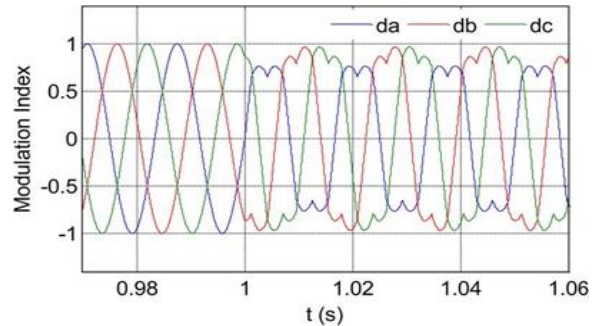


Fig. 7. Modulation indices before and after modulation compensation

TABLE I SYSTEM PARAMETERS

Parameters	Value
DC-link capacitor	3600 μ F
Connection inductor L	2.5 mH
Grid resistor R	0.1 ohm
Grid rated phase voltage	60 Vrms
Switching frequency	1.5 kHz

By injecting a zero sequence modulation index at $t = 1$ s, the balanced modulation index will be updated, as shown in Fig. 7. It can be seen that, with the compensation, the updated modulation index is unbalanced proportional to the power, which means that the output voltage (v_{jN}) of the three-phase

inverter is unbalanced, but this produces the desired balanced grid current.

V. SIMULATION RESULTS

Simulation and experimental tests are carried out to validate the proposed ideas. A modular cascaded multilevel inverter prototype has been built in the laboratory. The MOSFET IRFSL4127 is selected as inverter switches operating at 1.5 kHz. The control signals to the H-bridge inverters are sent by a dSPACE ds1103 controller.

A three-phase seven-level cascaded H-bridge inverter is simulated and tested. Each H-bridge has its own 185-W PV panel (Astronergy CHSM-5612M) connected as an independent source. The inverter is connected to the grid through a transformer, and the phase voltage of the secondary side is 60 Vrms. The system parameters are shown in Table I.

To verify the proposed control scheme, the three-phase grid-connected PV inverter is simulated in two different conditions. First, all PV panels are operated under the same irradiance $S = 1000 \text{ W/m}^2$ and temperature $T = 25 \text{ }^\circ\text{C}$. At $t = 0.8 \text{ s}$, the solar irradiance on the first and second panels of phase a decreases to 600 W/m^2 , and that for the other panels stays the same. The dc-link voltages of phase a are shown in Fig. 8. At the beginning, all PV panels are operated at an MPP voltage of 36.4 V. As the irradiance changes, the first and second dc-

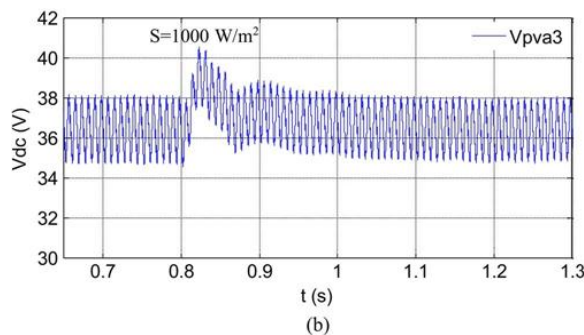
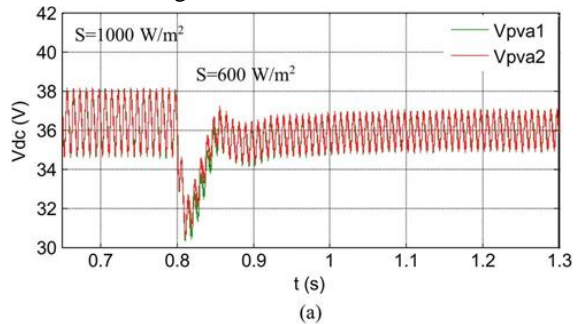


Fig. 8. DC-link voltages of phase a with distributed MPPT ($T = 25 \text{ }^\circ\text{C}$) (a) DC-link voltage of modules 1 and 2. (b) DC-link voltage of module 3

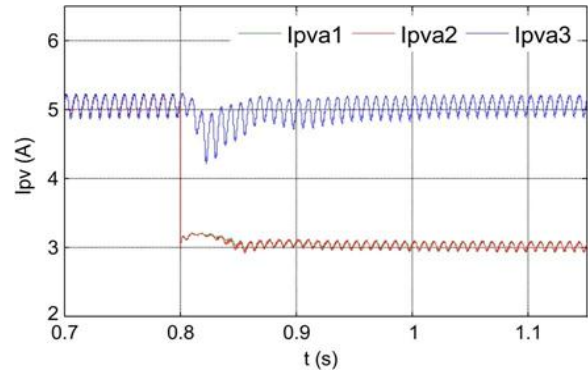


Fig. 9. PV currents of phase a with distributed MPPT ($T = 25 \text{ }^\circ\text{C}$).

link voltages decrease and track the new MPP voltage of 36 V, while the third panel is still operated at 36.4 V. The PV current waveforms of phase a are shown in Fig. 9. After $t = 0.8 \text{ s}$, the currents of the first and second PV panels are much smaller due to the low irradiance, and the lower ripple of the dc-link voltage can be found in Fig. 8(a).

The dc-link voltages of phase b are shown in Fig. 10. All phase- b panels track the MPP voltage of 36.4 V, which shows that they are not influenced by other phases. With the distributed MPPT control, the dc-link voltage of each H-bridge can be controlled independently. In other words, the connected PV panel of each H-bridge can be operated at its own MPP voltage and will not be influenced by the panels connected to other H-bridges. Thus, more solar energy can be extracted, and the efficiency of the overall PV system will be increased.

Fig. 11 shows the power extracted from each phase. At the beginning, all panels are operated under irradiance

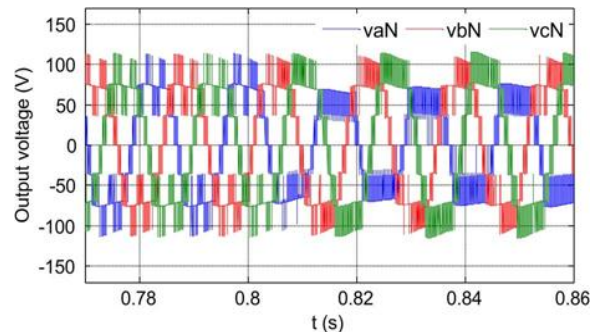


Fig. 10. DC-link voltages of phase b with distributed MPPT ($T = 25 \text{ }^\circ\text{C}$).

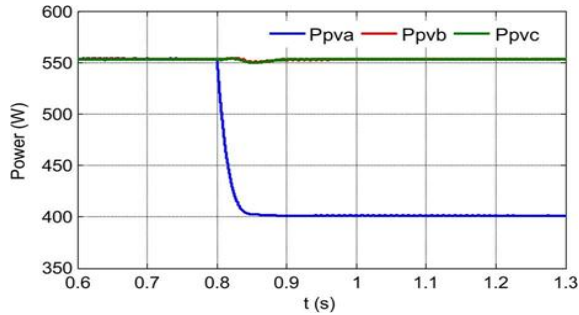


Fig. 11. Power extracted from PV panels with distributed MPPT

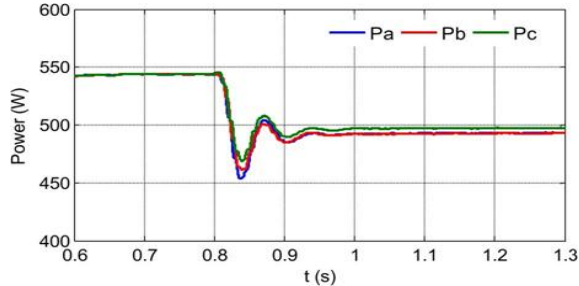


Fig. 12. Power injected to the grid with modulation compensation

$S = 1000 \text{ W/m}^2$, and every phase is generating a maximum power of 555 W. After $t = 0.8 \text{ s}$, the power harvested from phase a decreases to 400 W, and those from the other two phases stay the same. Obviously, the power supplied to the three-phase grid-connected inverter is unbalanced. However, by applying the modulation compensation scheme, the power injected to the grid is still balanced, as shown in Fig. 12. In addition, by comparing the total power extracted from the PV panels with the total power injected to the grid, it can be seen that there is no extra power loss caused by the modulation compensation scheme.

Fig. 13 shows the output voltages (v_{jN}) of the three-phase inverter. Due to the injected zero sequence component, they are unbalanced after $t = 0.8 \text{ s}$, which help to balance the grid current shown in Fig. 14.

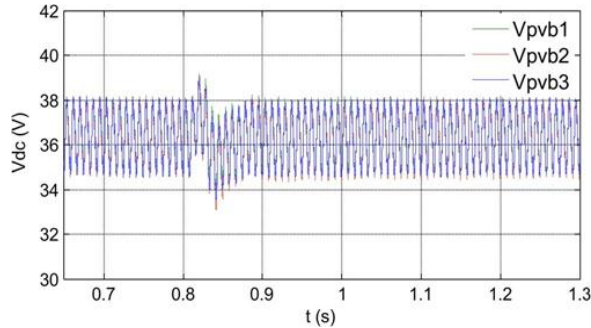


Fig.13. Three-phase inverter output voltage waveforms with modulation compensation

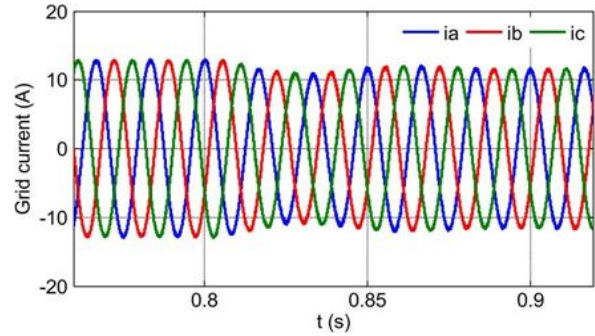


Fig. 14. Three-phase grid current waveforms with modulation compensation

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