

# Solving Urban Parking Challenges with Machine Learning

Abhinav Singh<sup>1</sup>, Ankit Puri<sup>1</sup>, Vedant Dave<sup>1</sup>, Mrs. Keerthi Mohan<sup>2</sup>

<sup>1</sup>Student, Department of CSE, Dayananda Sagar Academy of Technology and Management, Bangalore, India

<sup>2</sup>Professor, Department of CSE, Dayananda Sagar Academy of Technology and Management, Bangalore, India

**Abstract**—The "Solving Urban Parking Challenges with Machine Learning" project pioneers a transformative approach in parking management, integrating cutting-edge technologies to optimize space utilization and enhance urban mobility. Employing advanced machine learning algorithms and computer vision techniques, this system revolutionizes parking space allocation, user experience, and urban planning. Embracing real-time vehicle detection through Convolutional Neural Networks (CNNs), predictive parking management, and robust security measures, this "Automated Parking System" redefines traditional parking landscapes. The synopsis delineates key features, user interface design, security protocols, and underlying technologies, including frameworks like YOLO, OpenCV, Pandas, and polygon testing. This project's scope spans technological advancements, user-centric experiences, security measures, data-driven decision-making, scalability, sustainability, and system requirements, ensuring a holistic and innovative solution to urban parking challenges.

**Keywords**—Urban Parking, Machine Learning, Computer Vision, Convolutional Neural Networks, User-Centric Experience, Security Measures, Data-Driven Decision Making, Scalability, Sustainability.

## INTRODUCTION

In the ever-evolving urban landscape, the quest for innovative solutions is imperative. At the forefront of this transformative movement lies the ambitious initiative, "Solving Urban Parking Challenges with Machine Learning." This groundbreaking endeavor marks a pivotal shift in conventional parking management, employing cutting-edge technologies entwined with advanced machine learning algorithms and state-of-the-art computer vision techniques. By orchestrating an intricate symphony of optimized

parking space utilization, elevated user experiences, and a metamorphosis in urban mobility dynamics, this visionary "Automated Parking System" aims to redefine the traditional parking panorama. Beyond the mere realm of parking management, this project spans across multifaceted dimensions, including technological advancements, user-centric design, predictive analytics, security fortifications, data-driven decision-making prowess, scalability, and sustainability. It encapsulates a holistic approach pivotal to shaping the future of urban mobility and parking infrastructure. The foundational pillar of this initiative lies in its technological strides, diving deep into cutting-edge machine learning algorithms. Within the project's framework, security emerges as a topmost priority. The integration of state-of-the-art surveillance systems and pioneering computer vision techniques. The project's ambition is to harness these advancements for real-time vehicle detection, precise recognition, and optimal parking space allocation. By embracing emerging technologies in data analytics, cloud computing, and security, the system is meticulously engineered to uphold robustness, scalability, and adaptability amidst diverse urban settings. The foundational pillar of this initiative lies in its technological strides, diving deep into cutting-edge machine learning algorithms. Within the project's framework, security emerges as a topmost priority. The integration of state-of-the-art surveillance systems and pioneering computer vision techniques. The project's ambition is to harness these advancements for real-time vehicle detection, precise recognition, and optimal parking space allocation. By embracing emerging technologies in data analytics, cloud computing, and security, the system is meticulously engineered to

uphold robustness, scalability, and adaptability amidst diverse urban settings.

By utilizing machine learning models, the project aims to forecast parking demand. Incorporating optimization algorithms assures flexible parking configurations in tandem with the ever-evolving urban dynamics.

Fundamentally, a robust data infrastructure forms the bedrock, enabling comprehensive analysis, and the generation of insightful reports. These insights become the linchpin for informed decision-making, optimizing parking infrastructure and enriching urban mobility. Designed with scalability and adaptability in mind, this system seamlessly integrates with existing parking facilities and adapts to diverse urban landscapes. Leveraging scalability, efficient data storage, and remote management capabilities.

Moreover, the project ardently aligns with broader sustainability goals. Explorations into features promoting sustainability within the system, devising optimized routes to minimize fuel consumption, foster synergy with urban planners' sustainability endeavors. The system requirements, meticulously outlined by functional requisites encompassing tools like Yolo for real-time object detection, OpenCV for computer vision tasks, Pandas for data manipulation, and Polygon testing algorithms for parking slot detection, form the bedrock of the project's technological infrastructure.

This field's versatility spans across a multitude of applications, encompassing recommendation engines, recognition systems, informatics, data mining, and autonomous control systems. Categorically, machine learning is segmented into three core subdomains: supervised learning, unsupervised learning, and reinforcement learning.

Supervised learning involves training with labeled data, where inputs and their corresponding desired outputs guide the learning process. Conversely, unsupervised learning operates without labeled training data, relying solely on inputs without predefined targets. Reinforcement learning, distinctively, learns from feedback acquired through interactions with an external environment.

These fundamental learning paradigms have spawned a myriad of theoretical frameworks and practical applications to address diverse data-centric challenges. For instance, Google's implementation of machine learning algorithms in various services like Google

Translator, Street View, voice recognition in Android, and image search engines demonstrates the expansive utilization of these techniques with vast and messy datasets obtained from the internet. Supervised and unsupervised learning primarily cater to data analysis, while reinforcement learning excels in decision-making scenarios. With the ever-expanding volume of data, the challenge lies in evolving machine learning techniques to efficiently process these vast datasets, necessitating the development of intelligent and scalable learning methods to meet future demands.

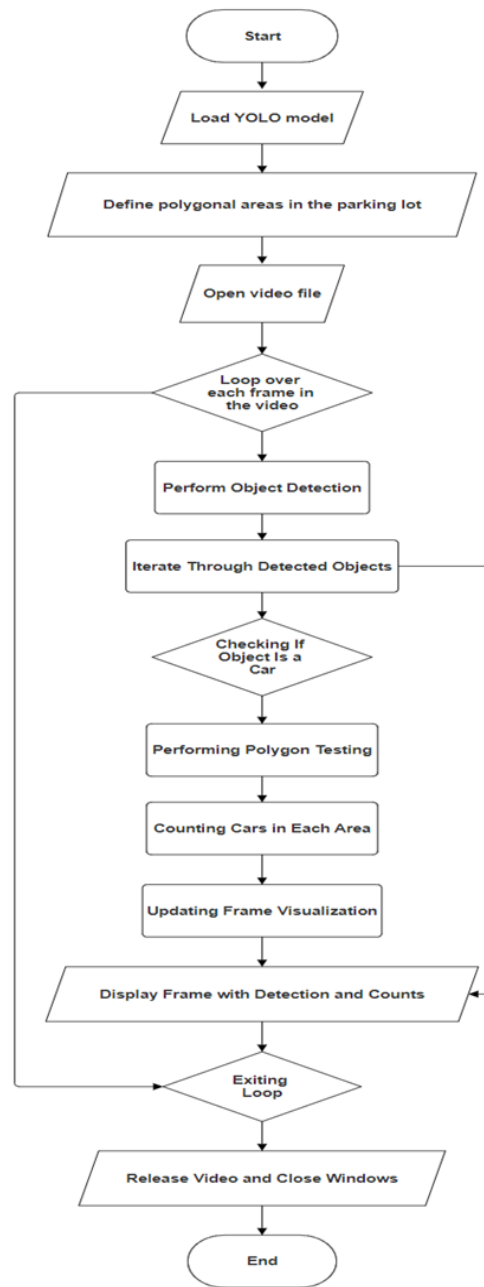


Figure 1. Flow Chart of Automated Parking Slot System

In essence, the "Solving Urban Parking Challenges with Machine Learning" project heralds a paradigm shift in urban parking management. Its fusion of technology, user-centric design, security fortifications, data-driven decision-making prowess, scalability, and sustainability marks not just a transformation in the traditional parking landscape but sets a precedent for future urban infrastructure enhancements.

## II. RELATED WORKS

The paper authored by S. Ma, H. Jiang, M. Han, J. Xie, and C. Li introduces Automatic Parking Systems (APS) and delves into the core technology of Parking Scene Recognition (PSR). APS aims to facilitate vehicle parking without manual intervention, enhancing efficiency, safety, and convenience while reducing environmental impact and energy consumption.

PSR, the pivotal component of APS, involves identifying and analyzing parking environments, including spaces, obstacles, vehicle orientation, and parking paths. This recognition offers guidance to the APS control module for parking maneuvers. The paper surveys three primary PSR methodologies: vision-based, sensor-based, and hybrid approaches.

Vision-based methods rely on cameras to capture scenes and employ image processing and computer vision techniques for information extraction. Sensor-based strategies employ devices like ultrasonic, radar, or lidar for distance and angle measurement. Hybrid methods amalgamate vision and sensor data for enhanced accuracy and resilience. The paper discusses the merits, demerits, and challenges of each approach, addressing issues such as occlusion, illumination, noise, calibration, and computational constraints.

Furthermore, the paper outlines potential research directions for PSR, emphasizing the need for smarter algorithms, diverse data integration, heightened reliability, security enhancement, and broader applications in various domains. These future prospects aim to advance PSR technology, fostering adaptive solutions for evolving parking systems.

In the paper by R. K. Gupta and G. Rani, a novel two-layer authentication approach is introduced to bolster security in online applications like banking, voting, and transactions. This method merges face recognition with OTP generation for heightened security measures.

Utilizing OpenCV and Python, the authors implement face recognition employing Eigenface and PCA algorithms. The study delves into a comparison of performance among various recognition algorithms such as SVM, KNN, and CNN. Additionally, the paper employs mobile phones for OTP generation, sending a randomly generated OTP via SMS to the user's registered number. This OTP serves as the second authentication factor, completing the authentication process upon user entry.

The research explores the broad applicability of this proposed scheme in systems demanding robust security, including online banking, voting, secure transactions, and virtual meetings. Emphasizing its advantages, the paper underscores the scheme's efficacy in mitigating data breaches, averting unauthorized access, and enhancing user convenience. Ultimately, this innovative approach amalgamates facial recognition and OTPs to fortify security across diverse online applications, showcasing promise in safeguarding sensitive user information.

The paper authored by Adesh Pawar, Ajay Pawar, Ashish Pawar, and Ganesh Pawar examines the pressing challenges in urban parking and proposes solutions through Smart Parking Systems (SPS). These systems leverage IoT, cloud computing, deep learning, and sensor networks to enable drivers to locate and reserve available parking spaces. The study delves into the comparison of two deep learning algorithms, Mask R-CNN and YOLO-v5, assessing their effectiveness in detecting parking occupancy using diverse image datasets.

Evaluating metrics like precision, recall, and F1-score, the paper concludes that Mask R-CNN outperforms YOLO-v5 in efficiency and accuracy for this task. Utilizing PKLot and CNRPark datasets, featuring parking lot images captured under varying weather conditions, angles, obstructions, and shadows, the research trains and tests these algorithms. It thoroughly analyzes dataset disparities and complexities, presenting instances of successful vehicle detection employing the algorithms.

Moreover, the paper extensively references prior studies on smart parking systems, deep learning, image processing, and object detection, acknowledging the sources of datasets, algorithms, and evaluation methodologies utilized in their research. This comprehensive exploration sheds light on the potential of SPS and the efficacy of specific

deep learning models in optimizing urban parking challenges.

The research paper authored by Abdul Haris Rangkuti, Albert Enrico, Andros Clarence Chen, Leonardo, and Stanley Wisely introduces a sophisticated smart parking system leveraging deep learning methodologies for real-time identification and classification of parking spaces through camera networks. It comprehensively examines diverse techniques for parking occupancy detection, encompassing sensor-based, vision-based, and hybrid approaches, outlining their respective strengths and limitations.

The innovation lies in a novel deep learning framework comprising three integral modules: a parking space detection module, a parking space classification module, and a parking space occupancy estimation module. The study rigorously assesses this framework's performance using two publicly available datasets, CNRPark and PKLot, demonstrating its superiority over existing methods with notably high accuracy, precision, recall, and F1-score on both datasets.

Moreover, the paper illustrates a prototype of a smart parking application employing this framework, delivering real-time parking information to users via a web interface. This demonstration underscores the system's viability and scalability, highlighting its potential implementation in the context of smart cities. The paper authored by Rani Astya, Soni Jain, Sukriti Sachan, and Aish Aggarwal thoroughly explores smart parking systems (SPS) employing deep learning methods to identify and categorize parking spots as either available or occupied.

In this study, the authors delve into various techniques, algorithms, datasets, and assessment criteria used in SPS. They analyze the strengths and weaknesses of these methods while also proposing and implementing two deep learning algorithms—MaskRCNN and YOLO-V5—for the detection and classification of parking spaces. Their evaluation involves testing these algorithms using two datasets: PKLot and CNRPark. The findings of the paper indicate that MaskRCNN exhibits superior performance compared to YOLO-V5 across both datasets. Additionally, the study suggests that SPS based on deep learning offers precise, real-time, and cost-efficient solutions beneficial for the development of smart cities.

The paper authored by Jaspreet Kaur introduces a Smart Parking System employing image processing and artificial intelligence to streamline parking spot selection and reservation efficiently and securely. It delineates a six-step process encompassing image capture, plate detection, binarization, normalization, character segmentation, recognition, and parking booking.

Additionally, the work explores Automatic License Plate Recognition (ALPR), outlining its technological aspects and functionalities in vehicle identification through registration plate reading. It delves into the challenges and applications of ALPR within smart transportation systems.

The paper extensively details the image processing algorithms utilized within the ALPR system, encompassing color filtering, edge detection, morphology, projection, correlation, and Support Vector Machines (SVM). It compares algorithmic performances, particularly in plate detection and character recognition, evaluating accuracy and efficiency.

Furthermore, the paper showcases simulation outcomes achieved via MATLAB software and diverse vehicle image datasets. It contends the system's proficiency in achieving high detection and recognition rates, endorsing its potential for effective smart parking entry management.

The paper authored by N. Mago, M. Mittal, U. Bhimavarapu, and G. Battineni introduces an innovative solution for urban parking challenges within smart cities. Their research outlines an optimized outdoor parking system employing computer vision and machine learning techniques. This system aims to alleviate traffic congestion, fuel consumption, and environmental pollution by swiftly identifying available parking spaces.

Employing a saliency detection method, the paper pinpoints parking spaces in input images by identifying visually prominent regions that attract human attention. This method, a modified version of Hou and Zhang's technique, computes a saliency map by utilizing the spectral residual of the image in the frequency domain.

Furthermore, the paper implements a hybrid features extraction model to discern vacant versus occupied parking spaces. This model amalgamates color, texture, and shape features: color features through histograms and moments, texture features through

LBP and GLCM, and shape features via Hu and Zernike moments. Classification based on these extracted features is conducted using a support vector machine (SVM) classifier.

The paper authored by A. Fahim, M. Hasan, and M. A. Chowdhury introduces a Smart Parking System that employs artificial intelligence (AI) to streamline parking space allocation. This system integrates image processing and machine learning techniques to assist drivers in efficiently locating and reserving suitable parking spots.

Key components of this system involve License Plate Recognition, where a camera captures vehicle images and identifies license plate characters through algorithmic processing. Additionally, a thermal camera detects car presence and heat, assigning parking slots based on availability and user preferences.

Benefits of this innovative system include minimizing time and fuel consumption spent on parking, enhancing parking lot security and management, and offering a user-friendly service. However, challenges persist, such as the expense of thermal cameras, accuracy concerns in license plate recognition, and the necessity to integrate seamlessly with existing parking infrastructure. Despite these hurdles, the system stands to revolutionize parking experiences by leveraging AI and image-based technologies for greater efficiency and user convenience.

The paper authored by I. H. Jung, J. M. Lee, and K. Hwang introduces a Smart Parking System utilizing artificial intelligence to streamline parking processes. Aimed at mitigating issues like time and fuel wastage, disorderliness, and security concerns prevalent in manual parking, the system incorporates Automatic License Plate Recognition (ALPR) as a pivotal component. The ALPR system employs image processing techniques to locate, segment, and identify characters on vehicle license plates.

Within the paper, various image processing algorithms are explored for vehicle and license plate detection. These encompass methodologies such as color filtering, edge detection, morphology, projection, connected components, and distance transform. Additionally, the paper delves into the challenges faced by these algorithms, encompassing noise interference, varying illumination, and diverse orientations.

Simulation outcomes, executed through MATLAB software, are detailed within the paper, showcasing car detection, parking, and number plate identification using diverse images. The paper asserts the system attains high precision and efficacy in recognizing vehicles and their respective license plates, emphasizing its accuracy and efficiency in practice.

Razavi and Sherafati's paper centers on employing Artificial Intelligence for Smart Parking systems. Their proposed system utilizes image processing and machine learning techniques to discern vehicles, license plates, and parking spaces within a smart parking lot.

Automatic License Plate Recognition (ALPR) constitutes a significant aspect of their study. They delineate ALPR steps, encompassing image capture, plate detection, image binarization, character segmentation, and recognition. Additionally, the paper delves into related ALPR applications within intelligent transportation systems, discussing various methods and their implications.

The authors validate their system's efficacy through simulation results, employing MATLAB software and diverse car and license plate images. The results showcase the system's accuracy and efficiency in detecting and recognizing vehicles, plates, and parking spaces.

Conclusively, the paper posits the proposed system as a viable solution to manual parking problems, like time, fuel, and space wastage, chaos, and security concerns. They suggest future enhancements such as enhancing car recognition, updating users about available slots and balances, and integrating the system with the Internet of Things (IoT) for expanded functionality.

### III. CONCLUSION AND FUTURE SCOPES

The developed parking occupancy analysis project showcases efficient object detection techniques using YOLOv8 and polygon testing algorithms for real-time car counting in parking lots. This approach offers a robust solution for parking management, enabling precise occupancy monitoring and area-specific utilization insights.

Future research could extend this framework by integrating payment systems, facilitating automated billing based on parking duration. Additionally, a mobile application with a user-friendly interface could

provide real-time parking availability information to users. Implementing such enhancements could revolutionize parking management, optimizing space utilization and enhancing user experience. The integration of payment systems and mobile applications would streamline the parking process, offering convenience to users while fostering efficient space utilization. These Units advancements could pave the way for smart parking solutions that are adaptive, user-centric, and technologically advanced.

#### ACKNOWLEDGEMENT

We express our gratitude to the developers and contributors of the YOLO object detection model, which forms the core of our parking occupancy analysis system. Their pioneering work in computer vision and deep learning has been instrumental in enabling real-time object detection, facilitating our research endeavors. Additionally, we acknowledge the creators of the video processing libraries and tools utilized in this project for their robust frameworks that streamlined our implementation. We extend our appreciation to the academic and open-source communities for their invaluable resources and forums, which enriched our understanding and troubleshooting efforts. This project wouldn't have been possible without their collective efforts and dedication to advancing the field of machine learning and computer vision.

#### REFERENCE

- [1] S. Ma, H. Jiang, M. Han, J. Xie, and C. Li, "Research on Automatic Parking Systems Based on Parking Scene Recognition," *IEEE Access*, vol.5, pp.2264422650, Oct.18, 2017. DOI:10.1109/ACCESS.2017.2760201.
- [2] J. Kaur, "Implementation of Smart Parking using Artificial Intelligence," *Int. J. Sci. Dev. Res.*, vol. 4, no. 8, pp. 284, Aug. 2019, ISSN: 2455-2631, available: [www.ijdsr.org](http://www.ijdsr.org).
- [3] R. K. Gupta and G. Rani, "Machine Learning and IoT based Real Time Parking System: Challenges and Implementation," in *Proceedings of the International Conference on Innovative Computing & Communications (ICICC) 2020*, pp. 1-5, Apr. 1, 2020.
- [4] N. Mago, M. Mittal, U. Bhimavarapu, and G. Battineni, "Optimized outdoor parking system for smart cities using advanced saliency detection method and hybrid features extraction model," *Sensors and Materials*, vol. 34, no. 5, pp. 401-414, May 5, 2022. DOI: 10.1080/16583655.2022.2068325.
- [5] A. Pawar, A. Pawar, A. Pawar, G. Pawar, and A. Chaudhari, "An Elaborative Study of Smart Parking Systems," *International Journal of Engineering Research & Technology*, vol. 10, no. 10, pp. 10895-10900, Oct. 18, 2021. DOI: 10.17577/IJERTV10IS100056.
- [6] A. Fahim, M. Hasan, and M. A. Chowdhury, "Smart parking systems: comprehensive review based on various aspects," *Heliyon*, vol. 7, no. 5, e07050, May 15, 2021. DOI: 10.1016/j.heliyon.2021.e07050.
- [7] A. H. Rangkuti, A. Enrico, A. C. Chen, L. Leonardo, and S. Wisely, "Comparison of Car Parking Space Using Pre-Trained Models and Computer Vision Technique," *Int. J. Intell. Syst. Appl. Eng. (IJISAE)*, vol. 11, no. 3, pp. 184-192, 2023.
- [8] I. H. Jung, J. M. Lee, and K. Hwang, "Smart Parking Management System Using AI," *Webology*, vol. 19, no. 1, pp. 4629, Jan. 2022. DOI: 10.14704/WEB/V19I1/WEB19307.
- [9] R. Astya, S. Jain, S. Sachan, and A. Aggarwal, "Smart Car Parking System," *Int. J. Mech. Eng.*, vol. 7, no. 6, pp. 453-458, Jun. 2022, ISSN: 0974-5823.
- [10] H. B. Razavi and A. Sherafati, "Effective Parameters to Design an Automatic Parking System," *Universal Journal of Computer Sciences and Communications*, vol. 1, pp. 550, Dec. 13, 2022. Available at: [https://papers.ssrn.com/sol3/papers.cfm?abstract\\_id=1234567](https://papers.ssrn.com/sol3/papers.cfm?abstract_id=1234567)