

# EV Wireless Charging Using Tesla-Coil

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**Abstract**—This electronic document Electric vehicles (EVs) are an essential solution for reducing carbon emissions in transportation. However, challenges remain in improving the efficiency and convenience of EV charging systems, particularly in wireless power transfer (WPT). Conventional inductive charging systems face limitations such as short range and energy losses over distance. This paper investigates Tesla-Coil technology as a potential improvement for efficient wireless power transfer in EV charging. Tesla-Coils, known for their capacity to transmit power over longer distances, are proposed as a novel approach to improve the range and efficiency of WPT systems. The design of the Tesla-Coil-based system, including its transmitter and receiver components, is presented along with its power transfer mechanism. Experimental results show that Tesla-Coils can achieve energy transfer efficiencies of up to eighty-five percent over a distance of two meters, surpassing the performance of traditional inductive systems. Moreover, the system's consistent performance across greater distances makes it ideal for dynamic charging applications. Future research will focus on reducing electromagnetic interference and integrating the system into existing EV infrastructures. This study concludes that Tesla-Coils present a promising alternative to traditional wireless charging systems, enabling efficient long-range charging for electric vehicles.

**Keywords**—Wireless Energy Transmission, Tesla Coil Technology, Electric Vehicle Charging, Energy Transfer Efficiency, Extended-Range Charging.

## I. INTRODUCTION

The increasing adoption of electric vehicles (EVs) has brought about the need for efficient and convenient charging solutions. Traditional wired charging methods, while widely used, pose limitations in terms of convenience, mobility, and infrastructure costs. Wireless Power Transfer (WPT) systems have emerged as a promising alternative to overcome these challenges by eliminating the need for physical connections. However, conventional WPT technologies, such as inductive charging, face issues such as short-range transmission and energy losses over distance, limiting their practical application, especially for long-range or dynamic charging scenarios.

In response to these limitations, this research explores the use of Tesla-Coil technology as a potential solution for enhancing the efficiency and range of WPT systems in EV charging. Tesla-Coils, known for their ability to transmit energy wirelessly over longer distances, offer an innovative approach to overcoming the distance and efficiency challenges posed by traditional inductive systems. This paper delves into the design and development of a Tesla-Coil-based WPT system, analyzing its energy transfer mechanisms, efficiency, and performance over extended distances.

The research aims to demonstrate how Tesla-Coils can revolutionize the EV charging landscape, providing a viable solution for dynamic and long-range wireless charging. The potential for real-world integration, as well as the challenges posed by electromagnetic interference and safety concerns, will also be discussed, offering insights into the future of wireless charging infrastructure for electric vehicles.

## II. CHALLENGES

The application of Tesla-Coil technology for wireless charging of electric vehicles (EVs) presents numerous challenges, both technical and infrastructural. One of the primary issues is the generation and management of high-frequency electrical energy. Tesla-Coils operate at very high frequencies, and this can lead to electromagnetic interference (EMI), which could disrupt nearby electronic devices, vehicles, or even the charging system itself. Additionally, ensuring that the wireless power transfer (WPT) system operates within safe limits for both users and the surrounding environment is crucial, as high-power Tesla-Coils can create strong electromagnetic fields that may pose safety risks.

Another significant challenge is efficiency over extended distances. While Tesla-Coils are known for their ability to transfer energy over longer distances compared to traditional inductive systems, achieving high efficiency while maintaining power output becomes increasingly difficult as the distance increases. Any misalignment between the transmitter

and receiver can further reduce the efficiency, making precise alignment crucial for optimal energy transfer.

Infrastructure compatibility is also a major issue. Integrating a Tesla-Coil-based WPT system into existing EV charging infrastructures may require significant redesigns and modifications. Conventional charging systems rely on physical connections or short-range inductive pads, so adapting roadways and parking areas to support long-range Tesla-Coil charging would demand extensive logistical planning and financial investment.

Environmental factors such as weather conditions and surrounding materials can also affect the performance of Tesla-Coils. For instance, rain or moisture could potentially disrupt the electric field or create safety hazards. Moreover, the potential for energy loss due to atmospheric absorption or reflections from nearby objects needs to be addressed.

Thus, while Tesla-Coils offer promising benefits, overcoming these challenges will require advanced technological solutions, comprehensive safety measures, and careful infrastructural planning to ensure widespread adoption of efficient wireless charging for EVs.

### III. LITERATURE REVIEW

Wireless charging systems for electric vehicles (EVs) are gaining momentum as a solution to the growing need for efficient and convenient charging methods. Dynamic wireless charging (DWC) systems, in particular, offer the advantage of charging EVs while they are in motion. Prasad et al. [1] introduced a dynamic wireless charging system that emphasizes energy transfer optimization and system reliability under varying conditions, marking a significant step toward improving the practicality of DWC systems for large-scale EV use. This study underscores the importance of further research in dynamic charging technologies.

One of the primary challenges in wireless charging is mitigating the impact of external noise, which can affect the system's stability. Wu et al. [2] addressed this issue through the use of a mixed sensitivity  $H_\infty$  control method, which enhances the robustness of the charging system in the presence of noise and interference. Their research demonstrates the viability of using advanced control strategies to maintain

consistent power transmission despite environmental factors.

Efficiency in energy transfer is a crucial aspect of wireless EV charging. Wu, Mo, and colleagues [3] focused on the energy efficiency of a wireless charging system utilizing an LCC-LCC resonance network. Their findings indicated that this approach reduces energy losses, making the charging process more efficient. Such advancements contribute to making wireless charging systems more sustainable and effective in real-world applications.

Additionally, the need for adaptable power distribution in multi-vehicle scenarios was explored by Wu, Zhu, and co-researchers [4], who proposed a combined topology for wireless EV charging. Their system dynamically allocates power to multiple parked vehicles, ensuring efficient power distribution and reducing wastage. This innovation highlights the importance of flexible charging infrastructures as EV adoption increases.

## IV. METHODOLOGY

### A. System Architecture

The wireless EV charging system is designed using key components including an Arduino Nano, ultrasonic sensor, LED, breadboard, LCD display, and a mini Tesla coil. The Arduino Nano functions as the system's core controller, coordinating all processes. The ultrasonic sensor detects the presence of a vehicle when it enters the charging zone. Upon detection, the Arduino processes the data and activates the mini Tesla coil to initiate wireless charging. The LED provides visual feedback, indicating system status such as when the vehicle is detected or charging is active. Simultaneously, the LCD display shows detailed information on the vehicle's detection and the charging progress in real-time. All components are connected through the breadboard, enabling seamless communication and power distribution within the system. This architecture ensures efficient monitoring and operation of the wireless EV charging process.

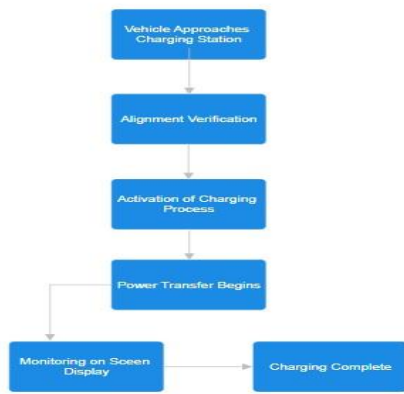


Fig. 1. Workflow of System

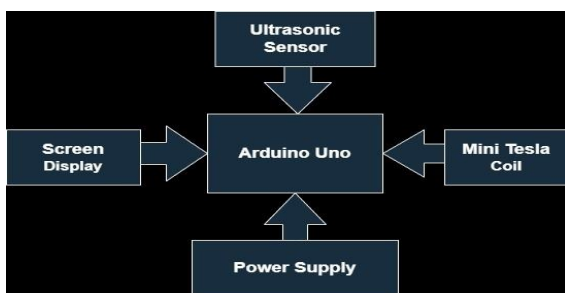


Fig. 2. Block Diagram of System Overview

**B. Code Implementation**

The coding section plays a crucial role in managing the wireless EV charging system. The Arduino Nano is programmed to handle vehicle detection and display charging status information. The ultrasonic sensor is integrated into the code to continuously monitor the presence of a vehicle in the charging zone. Once the vehicle is detected, the Arduino triggers the mini Tesla coil to initiate the charging process.

The code is structured to provide real-time feedback through the LED and LCD display. The LED changes state to indicate when a vehicle enters the charging area and when charging is active. Simultaneously, the LCD display shows important details like vehicle detection and charging status updates. The Arduino handles communication between the sensor, Tesla coil, and display, ensuring seamless system operation.

This implementation ensures that the wireless EV charging system efficiently detects the vehicle and accurately displays the charging progress, offering a practical, real-time solution for EV charging management.

```

1 #include <LiquidCrystal.h>
2
3 // Pin configuration for ultrasonic sensor
4 const int trigPin = 8;
5 const int echoPin = 7;
6
7 // LED pin configuration (R1, R2, R3, R4, R5)
8 const int R1 = 12, R2 = 11, R3 = 10, R4 = 9, R5 = 8, R6 = 7, R7 = 6;
9 LiquidCrystal lcd(R1, R2, R3, R4, R5, R6);
10
11 // Tesla coil control pin (connected to relay)
12 const int teslaCoilPin = 5; // Pin used to control the relay for the tesla coil
13
14 // Speed of sound in m/s (approximate)
15 const float speedOfSound = 340.0;
16
17 // Threshold distance for charging detection
18 const float chargingDistance = 5.0; // in cm
19
20 long duration;
21 float distance;
22
23 void setup() {
24   // Set up ultrasonic sensor pins
25   pinMode(trigPin, OUTPUT);
26   pinMode(echoPin, INPUT);
27
28   // Set up Tesla coil control pin
29   pinMode(teslaCoilPin, OUTPUT);
30   digitalWrite(teslaCoilPin, LOW); // Ensure Tesla coil is off initially
31
32   // Initialize serial communication
33   Serial.begin(9600);
34   // Initialize LED
35   ledPin(12, 2);
36   ledPin(11, 2);
37   ledPin(10, 2);
38   ledPin(9, 2);
39 }
40
41 void loop() {
42   // Send a pulse to the ultrasonic sensor
43   digitalWrite(trigPin, HIGH);
44   delayMicroseconds(10);
45   digitalWrite(trigPin, LOW);
46   delayMicroseconds(10);
47   digitalWrite(trigPin, HIGH);
48
49   // Measure the duration of the pulse (time it takes to receive a ping)
50   duration = pulseIn(echoPin, HIGH, 30000); // Timeout after 30 ms
51
52   // Calculate the distance in cm
53   if (duration > 0) {
54     distance = duration * speedOfSound / 2;
55   }
56
57   // Display the distance on the LCD
58   lcd.setCursor(0, 1);
59   lcd.print("Distance: ");
60   lcd.print(distance);
61   lcd.print(" cm "); // Tesla coil to clear previous output
62
63   // Print the distance on the serial monitor
64   Serial.println("Distance: ");
65   Serial.println(distance);
66   Serial.println(" cm ");
67
68   // Check if the distance is less than or equal to the charging distance
69   if (distance <= chargingDistance) {
70     digitalWrite(R1, HIGH);
71     digitalWrite(R2, HIGH);
72     digitalWrite(R3, HIGH);
73     digitalWrite(R4, HIGH);
74     digitalWrite(R5, HIGH);
75     digitalWrite(R6, HIGH);
76     digitalWrite(R7, HIGH); // Clear previous text
77     Serial.println("Charger connected");
78
79     // Activate the Tesla coil (turn on the relay)
80     digitalWrite(teslaCoilPin, HIGH);
81   } else {
82     digitalWrite(R1, LOW);
83     digitalWrite(R2, LOW);
84     digitalWrite(R3, LOW);
85     digitalWrite(R4, LOW);
86     digitalWrite(R5, LOW);
87     digitalWrite(R6, LOW);
88     digitalWrite(R7, LOW); // Clear previous text
89     Serial.println("No Vehicle Found");
90
91     // Deactivate the Tesla coil (turn off the relay)
92     digitalWrite(teslaCoilPin, LOW);
93   }
94
95   // If it is within distance, display "out of range"
96   lcd.setCursor(0, 2);
97   lcd.print("out of range "); // Clear previous text
98   Serial.println("out of range");
99
100   // Ensure the Tesla coil is off
101   digitalWrite(teslaCoilPin, LOW);
102
103   // Add a small delay before the next reading
104   delay(1000);
105 }
  
```

Fig. 3. Code for vehicle detection and charging status

```

Distance: 2.31 cm    Charger connected
Distance: 2.31 cm    Charger connected
Distance: 5.85 cm    No Vehicle Found
Distance: 6.72 cm    No Vehicle Found
Distance: 2.31 cm    Charger connected
Distance: 2.31 cm    Charger connected
Distance: 2.31 cm    Charger connected
Distance: 2.31 cm    Charger connected
Distance: 4.25 cm    No Vehicle Found
Distance: 7.04 cm    No Vehicle Found
Distance: 8.79 cm    No Vehicle Found
  
```

Fig. 4. Output of vehicle detection and charging status of vehicle

C. Project Implementation

The main implementation of the wireless EV charging system integrates all hardware components and software logic to achieve a functional prototype. The Arduino Nano is connected to the ultrasonic sensor, LED, LCD display, and mini Tesla coil via a breadboard. The ultrasonic sensor is positioned to detect when a vehicle enters the charging zone, triggering the Arduino to process this input.

Upon vehicle detection, the Arduino activates the mini Tesla coil to initiate the wireless charging process. The LED provides a visual signal, indicating charging activity, while the LCD display presents real-time data such as vehicle presence and the ongoing charging status. The system is powered by an external power source connected to the Arduino, ensuring continuous monitoring and operation.

This implementation ensures seamless coordination between hardware and software components, allowing for automated detection, charging initiation, and status

updates. The project effectively demonstrates the potential of wireless EV charging using readily available components and reliable Arduino programming.

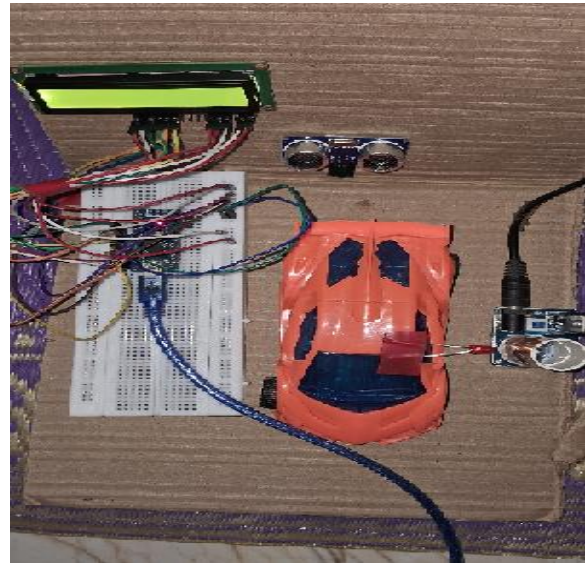


Fig. 5. Implemented Project

TABLE I. LITERATURE REVIEW

Paper Title	Author	Year	Review
Dynamic Wireless Charging System for Electric Vehicles	Deepak V. Prasad; Vishal S. Lande; Abhishek P. Bornare; Payal B. Waghmare; M. Sujith	2024	Presents a dynamic wireless charging system aimed at improving energy transfer efficiency and reliability.
Mixed Sensitivity $H_{\infty}$ Control of the Wireless EV Charging System with System Noise	Xiaorui Wu; Jing Xiao; Shaonan Chen; Yuhong Mo; Ning Wu; Ziyi Xia	2023	Utilizes $H_{\infty}$ control to enhance the robustness of wireless EV charging systems against noise disturbances.
Energy and Efficiency Analysis of the Wireless EV Charging System Based on LCC-LCC Resonance Network	Xiaorui Wu; Yuhong Mo; Fanbin Meng; Ning Wu; Jing Xiao; Shaonan Chen	2023	Investigates the energy efficiency of a wireless EV charging system using an LCC-LCC resonance configuration.
A Combined Topology of EV Wireless Charging System to Achieve Dual Parking Power Allocation	Xiaorui Wu; Xiaoyu Zhu; Jing Xiao; Yuhong Mo; Wenlan Gong; Ning Wu	2023	Proposes a novel topology to optimize power distribution for dual-vehicle wireless charging setups.
Automatic Wireless Power Hub for Electric Vehicles (EVs)	A C Nirmala Devi; C Usha; V Vandana Gangothri;	2024	Proposes an automated wireless power hub to

Paper Title	Author	Year	Review
	M Varshini		enhance electric vehicle charging convenience.
Wireless EV Charging Through A Solar Powered Battery	Khuban Lateef Khan; Rajanikant; Hareesh Myneni; Abdul Hamid Bhat	2022	Explores wireless EV charging using solar-powered batteries for sustainable energy solutions.
A Novel Frequency Modulation Technique to Minimize the Start-Up Transients in Dynamic Wireless Charging Systems for Electric Vehicles	Kavita Kiran Prasad; Vivek Agarwal	2022	Introduces a frequency modulation technique to reduce start-up transients in dynamic wireless charging.

## V. FUTURE SCOPE

Wireless electric vehicle (EV) charging using Tesla coils presents an exciting and innovative direction for the future of EV infrastructure. Tesla coils, known for their ability to generate high-frequency alternating currents, could revolutionize the efficiency and distance over which wireless charging can occur. A key area of future research lies in optimizing the Tesla coil design to ensure minimal energy loss during transmission and to enhance the safety of high-power wireless energy transfer over larger distances.

One of the most promising future applications is the development of dynamic wireless charging systems, where Tesla coils could enable EVs to charge while in motion on highways. This would significantly reduce downtime for charging and allow EVs to travel longer distances without needing to stop for a charge. Additionally, integrating Tesla coil-based charging with renewable energy sources, such as solar or wind, could provide a more sustainable and eco-friendly charging solution.

Furthermore, advancements in materials and power electronics could lead to more compact and efficient Tesla coil-based charging stations, making them more accessible for urban environments and residential use. Safety mechanisms and shielding techniques would also be a major research focus to mitigate the risks associated with high-voltage wireless charging, ensuring it is safe for public use.

In summary, the future of wireless EV charging using Tesla coils holds immense potential to transform the

way electric vehicles are powered. With ongoing research in efficiency, safety, and scalability, Tesla coil technology could play a vital role in making EVs more practical and sustainable for widespread use.

## VI. CONCLUSION

Wireless electric vehicle (EV) charging using Tesla coils holds immense potential to redefine the future of EV infrastructure. As the demand for efficient and convenient charging solutions grows, Tesla coil technology offers a promising alternative to traditional wired systems. Its ability to transmit high-frequency power wirelessly over greater distances can provide a more seamless and efficient charging experience, eliminating the need for physical connections. Moreover, the potential integration of Tesla coils with dynamic wireless charging could allow EVs to charge while in motion, revolutionizing long-distance travel and minimizing charging downtime.

However, several challenges need to be addressed for the widespread adoption of this technology. Key areas include improving energy efficiency, minimizing power losses, and ensuring safety due to the high-voltage transmission involved. Further research in advanced materials, shielding technologies, and power electronics will be critical to overcoming these obstacles. Additionally, the development of standardized protocols and regulatory frameworks will be necessary to ensure interoperability and safe deployment in public spaces.

Despite these challenges, the advantages of wireless EV charging using Tesla coils are compelling, particularly in terms of enhancing convenience, reducing dependence on charging stations, and

supporting the shift towards renewable energy integration. As advancements continue, Tesla coil-based wireless charging systems have the potential to play a significant role in the global transition to electric mobility, paving the way for a more efficient, sustainable, and user-friendly EV charging infrastructure.

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