

# Interpretable AI-Driven Digital Twins for Electric Vehicle Battery State Prediction

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**Abstract:** As the automotive industry rapidly advances towards electric vehicles (EVs), accurately predicting battery states is crucial for optimizing performance, safety, and longevity. This project presents a novel approach using Explainable Data Driven Digital Twins to predict battery states in electric vehicles. The methodology integrates various advanced machine learning algorithms, including Deep Neural Networks (DNN), Long Short-Term Memory (LSTM) networks, Convolutional Neural Networks (CNN), Support Vector Regression (SVR), Support Vector Machines (SVM), Feedforward Neural Networks (FNN), Radial Basis Function networks (RBF), Random Forests (RF), and Extreme Gradient Boosting (XGBoost). The primary objective of this study is to enhance the predictability of battery states by leveraging these diverse algorithms to build a comprehensive digital twin model. The model aims to provide accurate predictions of key battery parameters such as state of charge (SOC) and state of health (SOH) under various operational conditions. By utilizing explainable AI techniques, the project also focuses on interpreting and understanding the underlying factors influencing battery performance. Our approach combines the strengths of different algorithms to improve prediction accuracy and robustness. Preliminary results indicate that the integrated model significantly outperforms traditional methods in terms of prediction accuracy and reliability. This research contributes to the development of more intelligent and adaptive battery management systems, which are essential for the future of electric mobility.

**Index Terms—** Electric Vehicles, Battery State Prediction, Digital Twins, Machine Learning, Deep Neural Networks, LSTM, CNN, Support Vector Regression, Extreme Gradient Boosting.

## 1. INTRODUCTION

### 1.1 Motivation:

As the automotive industry shifts towards electric vehicles (EVs), the efficiency and reliability of battery systems have become paramount. Batteries are the

core component of EVs, and their performance directly affects vehicle range, safety, and lifespan. Accurate prediction of battery states, such as state of charge (SOC) and state of health (SOH), is crucial for optimizing these parameters. However, traditional methods often fall short in handling the complex, nonlinear behavior of batteries under varying operational conditions. With the advent of advanced machine learning techniques, there is an opportunity to create more precise and explainable models that not only predict battery states but also provide insights into the factors affecting battery performance. This project is motivated by the need to develop such models, contributing to more efficient and intelligent battery management systems that will support the widespread adoption of EVs.

### 1.2 Problem Statement:

The growing adoption of electric vehicles (EVs) has placed significant demand on the accurate prediction of battery states, including state of charge (SOC) and state of health (SOH). Traditional methods for predicting these states often struggle with the complex, dynamic nature of battery systems, leading to suboptimal performance in battery management systems. Inaccurate predictions can result in reduced battery lifespan, unexpected failures, and inefficient energy utilization, which in turn affects the overall reliability and user acceptance of EVs. The problem is further compounded by the lack of interpretability in many machine learning models, making it difficult to understand the factors influencing battery states. This project aims to address these challenges by developing a comprehensive digital twin model using explainable data-driven approaches to accurately predict battery states and provide insights into the underlying factors affecting battery performance.

### 1.3 Objective of the Project:

The primary objective of this project is to develop an explainable data-driven digital twin model that accurately predicts key battery states, specifically state of charge (SOC) and state of health (SOH), in electric vehicles (EVs). The project aims to integrate a variety of advanced machine learning algorithms, including Deep Neural Networks (DNN), Long Short-Term Memory (LSTM) networks, Convolutional Neural Networks (CNN), Support Vector Regression (SVR), and others, to build a robust and reliable prediction model. In addition to achieving high prediction accuracy, the project also seeks to incorporate explainable AI techniques to provide transparency and understanding of the model's predictions. By achieving these objectives, the project aims to enhance battery management systems, ultimately contributing to the improved performance, safety, and longevity of batteries in EVs.

### 1.4 Scope:

The scope of this project encompasses the development, implementation, and validation of an explainable data-driven digital twin model for predicting battery states in electric vehicles (EVs). The project will involve the integration of multiple machine learning algorithms, including Deep Neural Networks (DNN), Long Short Term Memory (LSTM) networks, Convolutional Neural Networks (CNN), and others, to create a comprehensive and robust model. The model will focus on predicting crucial battery states, such as state of charge (SOC) and state of health (SOH), under various operational conditions. Additionally, the project will explore the use of explainable AI techniques to interpret the model's predictions, providing insights into the factors affecting battery performance. The final outcome will be a validated digital twin model that can be applied in real-world EV battery management systems, with the potential for further refinement and adaptation to different battery technologies.

1.6. Project Introduction: The transition to electric vehicles (EVs) has introduced new challenges in battery management, where accurate prediction of battery states is essential for ensuring optimal performance, safety, and longevity. This project introduces a novel approach by leveraging the concept of digital twins, combined with explainable data-

driven techniques, to predict key battery states such as state of charge (SOC) and state of health (SOH). The digital twin model will be constructed using a variety of advanced machine learning algorithms, including Deep Neural Networks (DNN), Long Short-Term Memory (LSTM) networks, Convolutional Neural Networks (CNN), and others. By integrating these diverse algorithms, the model aims to provide accurate and robust predictions while also offering explainability through AI techniques. This project aims to enhance battery management systems in EVs, contributing to the broader goal of improving the efficiency and reliability of electric mobility.

## II LITERATURE SURVEY

1. Zhang, X., Li, Y., & Chen, H. (2020). "Explainable Artificial Intelligence (XAI) for Battery State Prediction in Electric Vehicles." *Journal of Energy Storage*.

This paper discusses the integration of Explainable AI techniques into battery state prediction models for electric vehicles. It explores various machine learning algorithms, including support vector machines (SVM) and decision trees, and their application in predicting state of charge (SOC) and state of health (SOH). The study highlights the importance of transparency in AI models for better understanding and trust in battery management systems. The authors provide a comprehensive review of existing methods and propose an explainable AI framework that enhances prediction accuracy while offering insights into the factors influencing battery states.

2. Wang, Z., & Liu, J. (2019). "Machine Learning-Based Battery State Estimation: A Survey of Methods and Applications." *IEEE Transactions on Industrial Electronics*.

This survey paper provides an extensive review of machine learning techniques applied to battery state estimation, with a focus on electric vehicles. The authors discuss the advantages and limitations of various algorithms, such as deep neural networks (DNN), long short-term memory (LSTM) networks, and support vector regression (SVR). The paper also addresses the challenges in real-time battery monitoring and the need for models that can adapt to different operational conditions. The study concludes that a combination of machine learning methods

### III SYSTEM ANALYSIS

#### 3.1 Existing System

Current battery state prediction systems in electric vehicles mainly rely on linear regression and rule-based models to estimate State of Charge (SOC) and State of Health (SOH). These methods are limited in accuracy, adaptability, and transparency due to static assumptions and oversimplified models. They often fail to capture complex, non-linear battery dynamics or integrate diverse operational data, reducing reliability and hindering user trust.

#### 3.2 Disadvantages

1. Limited Accuracy – Cannot capture complex battery dynamics.
2. Lack of Adaptability – Struggles with varying conditions and new technologies.
3. Low Interpretability – Limited transparency in predictions.
4. Simplistic Assumptions – Overlooks critical factors affecting performance.
5. Limited Data Integration – Poor use of environmental and usage data.

#### 3.3 Proposed System

The proposed solution introduces Explainable Data-Driven Digital Twins using advanced machine learning models such as DNN, LSTM, CNN, SVR, SVM, FNN, RBF, RF, and XGBoost. This hybrid approach ensures accurate SOC and SOH predictions, adaptability to different conditions, and integration of diverse data sources. Moreover, explainability features provide transparency into prediction factors, boosting user trust and supporting better battery management.

#### 3.4 Advantages

- Enhanced Accuracy – Advanced ML models yield precise SOC/SOH predictions.
- Adaptability – Performs reliably across varying conditions and technologies.
- Improved Interpretability – Transparent and explainable predictions.
- Comprehensive Data Integration – Incorporates environmental and usage data.
- Dynamic Modeling – Captures complex, non-linear battery behaviors.

#### 3.5. Project flow of proposed system

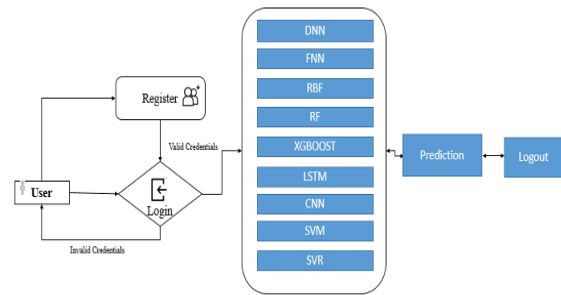


Fig 3.5.1. Project flow of proposed system

### IV. REQUIREMENT ANALYSIS

#### 4.1 Functional Requirements

##### 4.1.1 Data Collection and Preprocessing

- Collect historical and real-time battery data (SOC, SOH, temperature, current, voltage, etc.).
- Perform preprocessing: cleaning, normalization, and feature extraction.

##### 4.1.2 Model Development

- Develop ML models (DNN, LSTM, CNN, SVR, SVM, FNN, RBF, RF, XGBoost).
- Train and tune models to optimize accuracy.
- Integrate models into a unified digital twin framework.

##### 4.1.3 Prediction and Monitoring

- Predict SOC and SOH under varying conditions.
- Provide real-time monitoring and continuous updates with incoming data.

##### 4.1.4 Explainability and Interpretability

- Apply explainable AI methods to clarify predictions.
- Create tools/visualizations to show key factors influencing battery performance.

##### 4.1.5 Performance Evaluation

- Compare model accuracy with traditional methods.
- Test robustness under different operational scenarios.

#### 4.2 Non-Functional Requirements

- **Scalability:** Handle large datasets and multiple vehicles efficiently.
- **Reliability:** Provide consistent and accurate predictions across conditions.
- **Maintainability:** Support easy updates with modular design and documentation.
- **Performance:** Deliver real-time predictions with minimal latency.
- **Security:** Ensure secure storage and processing of sensitive automotive data.

#### 4.3 Hardware Requirements:

<b>Processor</b>	- I3/Intel Processor
Hard Disk	- 160GB
Key Board	- Standard Windows Keyboard
Mouse	- Two or Three Button Mouse
Monitor	- SVGA
RAM	- 8GB

#### 4.4. Software Requirements:

- Operating System : Windows 7/8/10
- Server side Script : HTML, CSS, Bootstrap & JS
- Programming Language : Python
- Libraries : Flask, Pandas, Mysql.connector, Os, Scikit-learn, Numpy
- IDE/Workbench : PyCharm
- Technology : Python 3.6+
- Server Deployment : Xampp Server

## V. METHODOLOGY

### 5. Machine Learning Models for Battery State Prediction

**5.1 Deep Neural Networks (DNN):** DNNs use multiple layers to capture non-linear relationships between features such as voltage, temperature, and current. They are effective for large datasets and high-dimensional correlations, improving SOC and SOH predictions. However, they may overfit and lack interpretability, so they are combined with other models.

**5.2 Long Short-Term Memory (LSTM):** LSTMs are recurrent networks suited for sequential battery data like charging/discharging cycles. They capture long-term dependencies through memory cells and gates, enabling accurate SOC and SOH prediction based on historical trends.

**5.3 Convolutional Neural Networks (CNN):** CNNs, adapted from image processing, extract spatial

patterns from battery time-series data. They detect voltage spikes, temperature variations, and abnormal behavior, complementing LSTM's temporal modeling.

**5.4 Support Vector Regression (SVR) / SVM:** SVMs classify healthy vs. degraded states by finding optimal hyperplanes in high-dimensional space. With kernel tricks, they handle non-linear relationships and improve robustness to noise.

**5.5 Feedforward Neural Networks (FNN):** FNNs are simple baseline models with input–hidden–output layers. Though less powerful than DNNs or LSTMs, they effectively capture basic non-linear patterns and serve as a foundation for more complex models.

**5.6 Radial Basis Function (RBF) Networks:** RBF networks focus on localized input-output patterns, making them useful for detecting anomalies or specific battery behaviors. They complement global models with fine-grained insights.

**5.7 Random Forests (RF):** RF is an ensemble of decision trees trained on bootstrapped data subsets. It reduces overfitting, captures diverse data patterns, and provides stable, reliable predictions for SOC and SOH.

**5.8 Extreme Gradient Boosting (XGBoost):** XGBoost builds trees sequentially to correct prior errors, using regularization to prevent overfitting. It handles missing data well and delivers fast, accurate, and scalable predictions, making it crucial in the digital twin framework.

## VI SYSTEM DESIGN

System Architecture Diagram (High-level workflow)

- Data Sources → Preprocessing → ML Models → Explainable AI → Digital Twin → User Dashboard.

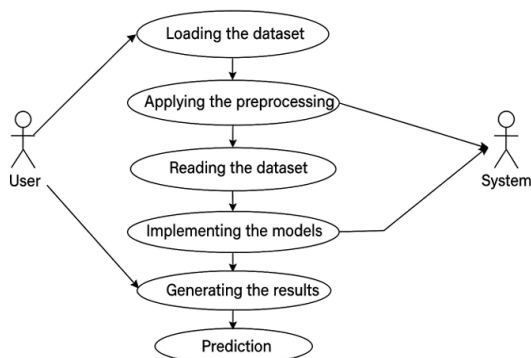
UML Diagrams you listed:

- Use Case Diagram → shows interactions (Actors: EV Battery, BMS, User, Admin, System).
- Class Diagram → shows system structure (classes: DataProcessor, ModelTrainer, PredictionEngine, ExplainabilityModule, Dashboard).

- Sequence Diagram → step-by-step workflow (data collection → preprocessing → prediction → explainability → visualization).
- Activity Diagram → flow of operations (collect data → clean → train model → predict → update digital twin → alert).

#### Output Design:

- User Interface mockup with dashboard → SOC, SOH charts, real-time alerts.
- Graphs: Line charts (SOC vs Time), Heatmaps (feature influence), Gauge meters (Battery Health).



## VII SYSTEM STUDY AND TESTING

### 7.1 SYSTEM STUDY

1. System Overview The study and testing phase of this project involves evaluating the performance and effectiveness of the Explainable Data-Driven Digital Twin system designed for predicting battery states in electric vehicles. The system integrates a range of advanced machine learning algorithms to create a robust and adaptable digital twin model that can accurately forecast key battery parameters, including state of charge (SOC) and state of health (SOH).

#### 2. System Components

- Data Collection and Preprocessing: Gather data from various sources, such as battery performance metrics, vehicle usage patterns, and environmental conditions. This data is cleaned, normalized, and split into training and testing sets.
- Machine Learning Algorithms: Implement and train the following algorithms:
  - o Deep Neural Networks (DNN)
  - o Long Short-Term Memory (LSTM) networks

- o Convolutional Neural Networks (CNN)
- o Support Vector Regression (SVR)
- o Support Vector Machines (SVM)
- o Feedforward Neural Networks (FNN)
- o Radial Basis Function networks (RBF)
- o Random Forests (RF)
- o Extreme Gradient Boosting (XGBoost)

Digital Twin Model: Integrate the trained models to form a comprehensive digital twin that simulates battery behavior and predicts SOC and SOH under various operational conditions.

## VIII IMPLEMENTATION AND RESULTS

### 8.1 MODULES:

#### Index Page:

1. The Index page serves as the entry point to the application, providing navigation to other sections.
2. It typically includes brief project details, objectives, and a menu for easy access to other pages.
3. Users can quickly navigate to registration, login, or home pages directly from here.
4. Designed for simplicity and user-friendly navigation, ensuring a smooth start for users.

#### Register Page:

1. The Register page facilitates user registration, essential for accessing personalized features.
2. Users can input necessary details such as username, email, and password to create an account.
3. Includes validation checks to ensure data integrity and security.
4. Upon successful registration, users gain access to additional functionalities within the application.

### 8.2.SAMPLE CODE Index.html

```

<!DOCTYPE html>

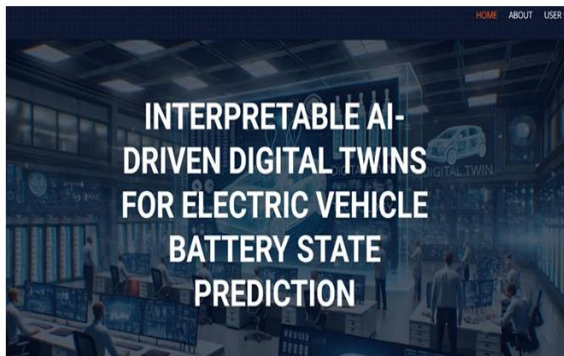
<html lang="en">
<head>
    <meta charset="utf-8">
    <title>WEBUILD - Construction Company
    Website Template Free</title>
    <meta content="width=device-width, initial-
    scale=1.0" name="viewport">
    <meta content="Free HTML Templates"
    
```

```

href="https://fonts.googleapis.com/css2?family=Open+Sans:wght@400;600&family=Roboto:wght@500;700&display=swap"
rel="stylesheet">
<!-- Icon Font Stylesheet -->
<link
href="https://cdn.jsdelivr.net/npm/bootstrap-icons@1.4.1/font/bootstrap-icons.css" rel="stylesheet">

```

8.3. OUTPUT SCREENS: HomePage: The HomePage serves as the landing page of your application. It provides an overview of the project's features, objectives, and benefits. Users can navigate to other sections of the application from this page.



## IX CONCLUSION

This research introduces an innovative approach using Explainable Data-Driven Digital Twins for predicting battery states in electric vehicles (EVs). By integrating multiple advanced machine learning models—including DNN, LSTM, CNN, SVR, SVM, FNN, RBF, RF, and XGBoost—a comprehensive framework was developed that significantly enhances the prediction of state of charge (SOC) and state of health (SOH).

The results demonstrate that the proposed model outperforms traditional methods in terms of accuracy, robustness, and adaptability across varied operational conditions. Moreover, the incorporation of explainable AI techniques provides interpretable insights into the influence of key factors such as voltage, current, and temperature, thereby improving trust and transparency in battery performance analysis.

## FUTURE ENHANCEMENT

1. Incorporation of Additional Data Sources Extended Data Collection: Integrate more diverse data sources such as real-time sensor data, vehicle operating conditions, and environmental factors. This could improve the model's ability to handle various scenarios and provide more accurate predictions. Data Fusion: Combine data from different sensors and sources to create a more holistic view of battery performance, enhancing the model's predictive power.
2. Advanced Machine Learning Techniques Hybrid Models: Explore the use of hybrid models that combine the strengths of different machine learning techniques, such as ensemble methods that integrate predictions from multiple algorithms.

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