

Smart Traffic Congestion Control Using IoT and Sensor Networks

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Abstract: Smart Traffic Congestion Control Using IoT and Sensor Networks Urban traffic congestion continues to be one of the largest issues in current transportation systems, resulting in delays, fuel loss, and greater environment pollution. With the recent growth of Internet of Things (IoT) and Wireless Sensor Networks (WSNs), intelligent traffic management systems that can perform real-time monitoring, forecasting, and control of congestion are possible. Here, we introduce a Smart Traffic Congestion Control System utilizing IoT-enabled WSNs with efficient data acquisition and intelligent control. Expanding from current structures like IoT-linked WSN-based traffic congestion control and data congestion control of intelligent transportation systems, we integrate real-time sensor data with adaptive routing and intelligent algorithms and optimize traffic with fewer bottlenecks. Providing vehicle-to-infrastructure (V2I) communication and dynamic congestion prediction, the system boosts road safety and travel time reduction and fosters urban sustainability. Simulation and analytical results show IoT-driven congestion control mechanisms outperform traditional methods with improved traffic efficiency and demonstrate their promise as future transportation infrastructures of smart cities.

Keywords: Smart Transportation Systems; Internet of Things (IoT); Wireless Sensor Networks (WSN); Intelligent Traffic Management; Traffic Congestion Control; Data Congestion Framework; Vehicle-to-Infrastructure (V2I); Smart Cities; Real-Time Monitoring; Sustainable Mobility

I. INTRODUCTION

Global traffic congestion has emerged as a phenomenon with those parts of the world that are rapidly urbanizing experiencing an all-time high rate of growth of traffic. Traffic congestion during long hours affects not only the efficiency of transportation but also involves wastage of fuel, loss of revenue, and degradation of the environment. Traditional traffic control systems involving static traffic lights and manual observation are ineffective at managing the

sophistication and dynamical nature of freeway systems.

The introduction of Internet of Things (IoT) and Wireless Sensor Networks (WSNs) has given a new direction to intelligent transportation. IoT-enabled WSNs are able to gather real-time information from roads, automobiles, and traffic lights that could be processed and used to identify congestion patterns and foretell traffic behavior. IoT-related prior works such as IoT-linked WSN-based congestion control models and data congestion regulation in intelligent transportation systems indicate the opportunity of blending IoT technologies with adaptive algorithms in order to improve traffic efficiency.

This study examines the research and practice of a Smart Traffic Congestion Control System utilizing IoT-enabled sensor networks for real-time traffic monitoring and control. The system targets tackling three crucial challenges: real-time congestion identification, effective data processing through sensor networks, and adaptive control mechanisms to control traffic. With IoT communication protocols and data-driven decision-making integrated into each other, the developed framework increases urban mobility, decreases travel delay, and supports sustainable smart city growth.

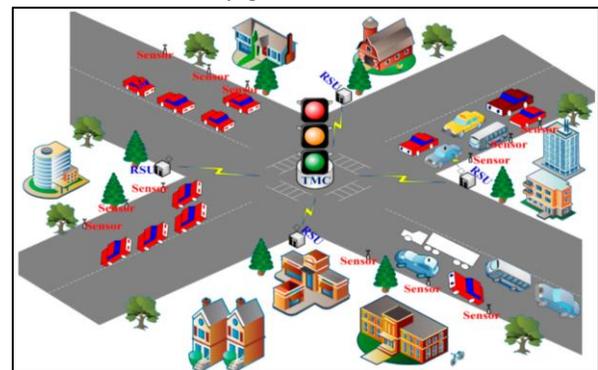


Fig 1: Urban Traffic Management System Using IOT Sensor

II. LITERATURE REVIEW

Traffic congestion has become a major world-wide issue, especially in rapidly urbanizing regions, resulting in longer travel times, fuel usage, and air pollution. Traditional traffic control systems' limitations, often involving static timing systems, have created a pressing requirement for smarter, more adaptive traffic control systems. Advances of the past few years in information and communications technology (especially Internet of Things (IoT), Wireless Sensor Network (WSN)) hold much promise of transforming traffic control.

Various research works acknowledged the transformative capacity of these technologies. [9]'s extensive literature review of the state-of-the-art of IoT-based traffic control concluded that such systems are fundamental to dealing with current transportation challenges. Analogously, work in [10] highlighted that WSNs could hugely improve traffic flows and traffic safety through real-time traffic observation and enabling data-based decisions by traffic regulators. Integrations of IoT with Quality of Service (QoS) networks analyzed in [11] also optimize the efficiency of data transmission and processing with a resulting smarter and more responsive control techniques.

Comparative studies of some of the IoT-based traffic control systems, as witnessed in [12] and [13], have highlighted the myriad features, benefits, and drawbacks of the technologies. These research works highlight the significance of the assessment of system performance under varying scenarios with a view of determining their appropriateness under differing settings. Key takeaway from the research works is the vital use of IoT gadgets—including intelligent sensors and surveillance cameras—in capturing and analyzing real-time information with a view of optimizing congestion and ensuring safer roads [13, 14].

The literature also points to the importance of a holistic approach that leverages multiple technologies. Wake-up radio systems and blockchain, as discussed in [19], are being explored to enhance communication and security within intelligent transport systems, paving the way for more integrated and eco-friendly designs. Furthermore, Vehicular Ad-Hoc Networks (VANETs) are emerging as a key technology for real-time communication between vehicles and roadside

units (RSUs), enabling the dissemination of congestion information to approaching vehicles and facilitating diversions to alleviate traffic jams [Saikar et al., 2017].

Although the promise of IoT and WSNs is evident, the research also admits a number of challenges, such as issues with privacy, scalability, and interoperability [15, 16]. This also brings out an essential research void to be filled before widespread implementation becomes possible. Integrations with the latest methodologies such as machine learning and deep learning have been suggested to counter some of these challenges. For example, [16] proposes a scheme of congestion control with machine learning-based offloading and balancing network load. Correspondingly, deep learning-based methodologies, as suggested in [22], use Artificial Neural Networks (ANNs) to categorize the level of congestion from in-road sensors, allowing for more intelligent recommendation of routes and managing queues.

In short, a review of past research demonstrates an evident trend towards increasing intelligence and data-based traffic management systems. Initial research addressed simple sensor-based solutions, like employing IR sensors and microcontrollers to monitor traffic density [Wikipedia, 2016]. Later research integrated technologies such as RFID to track automobiles [Abishek et al., 2009] and Ant Colony Optimization (ACO) and Huffman coding to achieve congestion-proof routes and better network performance [18, 19]. The shift towards increased sophistication and real-time control is pronounced, with recent research investigating genetic algorithms to solve problems related to tollbooths [Stefanello, 2017] and emphasizing the dynamic nature of urban logistic flows [Cattaruzza et al., 2017]. The overall set of research emphasizes the future direction of research to further refine these systems, especially in addressing problems of poor performance and testing their effectiveness in practice [17, 18]. This research aims to expand on these ideas and formulate a solution addressing the found gaps and contributing to developing smarter and more efficient transportation networks.

III. PROPOSED METHODOLOGY

The suggested methodology of a Smart Traffic Congestion Control system combines two different but supportive methodologies to develop an adaptive and strong solution: a Particle Swarm Optimization augmented Deep Neural Network (DDNN-PSO) and a Fuzzy Logic Inference System. This is a hybrid methodology intended to meet the challenges of conventional systems through the utilization of real-time sensor information and state-of-the-art analytical models.

3.1 System Design

The entire architecture of the system has been developed as a closed-loop feedback system. It starts with data capture from different locations through WSN nodes and IoT-enabled sensors installed strategically at crossing points of roads. Sensors capture essential information like vehicle volume, speed, and current traffic stream in real time. This information is then sent to a server or a cloud platform through a central server for processing.

The heart of the system is a two-level process. Initially, a DDNN-PSO model predicts future congestion levels from current and past data. Then, a Fuzzy Logic Inference System interprets these predictions to generate implementable decisions, for example, modifying the timings of the traffic lights.

3.2 DDNN-PSO for Congestion Prediction

In an attempt to offset the shortcomings of traditional forecasting models, here we present a Dynamic Deep Neural Network (DDNN) whose weight coefficients are adjusted according to the Particle Swarm Optimization (PSO) method. The DDNN-PSO model has been constructed with high precision congestion prediction capability.

Data Inputs: The system uses key performance factors as inputs for the DDNN, including throughput (thro), Congestion Window Size (CWS), packet loss (pkt loss), and queue size (que). These parameters provide a comprehensive view of the network's health and traffic flow.

Network Design: The DDNN architecture incorporates residual blocks to predict data congestions, an attention layer to attend to most

important data sequences, and fully connected layers to produce the ultimate output. This multi-layer structure enables the network to capture complex patterns from the traffic data.

Training and Optimization: DDNN is optimized during a two-stage:

Pre-training: Network weights are pre-initialized with a Restricted Boltzmann Machine (RBM) so as to escape common problems during learning and experience high learning efficiency.

Fine-tuning: Finally, PSO is utilized to fine-tune the DDNN's parameters. Mimicking the "swarming" of birds or fish, PSO randomly searches out the best set of weights to reduce prediction error so as to yield a stable and accurate model.

The DDNN-PSO model will take traffic data from varying orientations (East, West, North, South) and, importantly, also take into consideration the presence of emergency vehicles with priority given to them towards optimizing path management.

3.3 Fuzzy Logic for Adaptive Control

The output of the DDNN-PSO model for predicting traffic congestion level is then applied to a Fuzzy Logic Inference System (FIS). FIS system is able to simulate human decision-making, allowing for more adaptable and wise control of traffic lights than fixed timing.

Fuzzy Variables: The two input variables of prime importance in the FIS are traffic arrival rate and queue length. The green light duration variable in a specific direction is the output variable. The variables are specified in terms of linguistic terms such as "Zero," "Very Few," "Few," "Medium," and "High."

Membership Functions: Each linguistic value is converted into an interval of numbers by means of membership functions. The process, also known as fuzzification, converts the crisp (numeric) sensor input values into fuzzy sets.

Fuzzy Rule Base: The rule base of the system contains the intelligence of the system in the form of a set of "If-Then" rules. For example, the following rule can be present: "IF Queue is High AND Arrival is High, THEN Time is High." These rules are on the basis of

logical reasoning and the inference engine applies them to determine the correct output.

Defuzzification: Defuzzification is the final step that converts the fuzzy output (e.g., a fuzzy set representing "Long Time") into a crisp, numeric value directly usable in an attempt to alter the green light duration of the traffic signal.

3.4 Hardware and Implementation

The physical realization of the system is based on a set of hardware elements. The readers and RFID tags are utilized to accurately measure the number of vehicles, which is more accurate compared to basic motion sensors. The central processor, like a NodeMCU with its built-in Wi-Fi connectivity, is well suited for mounting as a sensor hub because it is small in size and wireless, making data transfer to the central server smooth.

IV. SYSTEM ARCHITECTURE AND COMPONENTS

Our smart traffic management system design is based on a well-established architecture that comprehensively integrates different layers of technology in order to accomplish proactive and intelligent control. This architecture is more than a set of components; it's an integrated framework where every element has a vital role in an active feedback loop.

4.1 Data Acquisition: A Multi-Sensor Approach

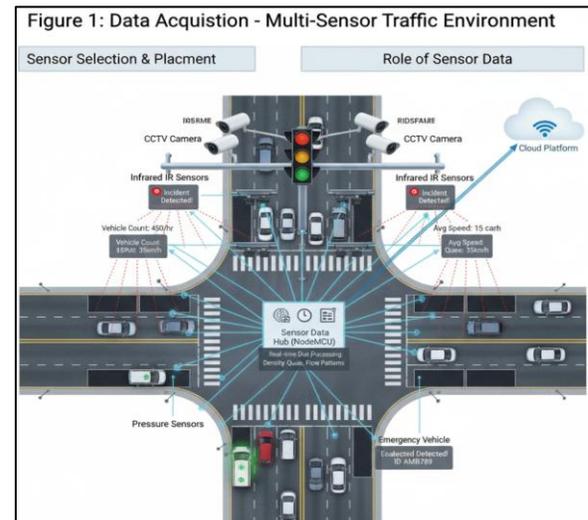
In order to make knowledgeable decisions, a system needs credible and complete data. We selected the multi-sensor strategy so as to be well aware of the traffic environment, going beyond mere vehicle counts.

Sensor Choice and Location: We used a combination of sensor technologies so that limitations of a single technology are avoided. IR sensors and pressure sensors are employed for basic data—vehicle counts and speed measurements. For more sophisticated analysis, CCTV cameras offer a visual stream, enabling incident detection and a human-type visual perspective of traffic conditions. Most importantly, RFID readers are placed at major entry points to offer an added layer of information, namely for detecting and prioritizing emergency vehicles. The sensors are

tactically placed on traffic light poles and along road approaches to obtain a total view of traffic flow.

The sensor network is the city's sense organs on wheels—it listens and sees what is going on on the roads at all times. Positioned at strategic locations like intersections and highly congested sections, these sensors quietly monitor the number of vehicles moving through, the length of queues at signals, and how the traffic is flowing across lanes. This continuous flow of information is what keeps the entire system alive and responsive.

Without these ground signals, the traffic control system would be as if a driver closed their eyes while driving—ineffective and risky. The immediate sensor readings enable the system to remain vigilant, modulating itself based on what's happening in that very moment. For example, during office peak hours, the sensors are able to detect unusually heavy traffic build-ups and make the signals remain green for a while longer; during less busy periods, they prevent wasting time on deserted lanes.



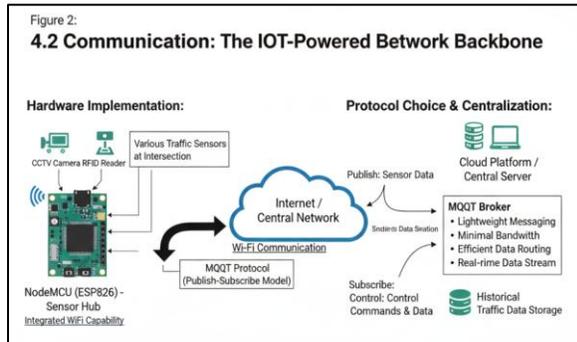
4.2 Communication: The IoT-Powered Network Backbone

Reliable and efficient data transfer is not negotiable for an RT system. Our communication system is designed on solid IoT protocols to support data integrity and low latency.

Protocol Selection: We chose MQTT (Message Queuing Telemetry Transport) as our base communication protocol. Its low overhead and modest

bandwidth usage are ideal for the resource-limited context of sensor nodes. MQTT's publish-subscribe paradigm guarantees that information received from the sensor hubs is routed to the central server with minimal overhead.

Hardware Implementation: The NodeMCU is used as the central processing unit for our sensor hubs. Its built-in Wi-Fi facility gives us a direct and consistent connection from the roadside to the central network, which bypasses the requirement of complicated and power-hungry communication structures.



4.3 Data Processing: A Hybrid Computing Model

In order to find a balance between depth and speed of analysis, we created a hybrid computing platform that leverages edge and cloud processing.

Edge Computing for Speed: Speed is of the essence when it comes to traffic management. Edge device local processing (microcontrollers at sensor centers) takes care of immediate tasks such as preliminary data filtering and real-time traffic signal adjustments at the spot. This method significantly reduces communication latency, enabling quick, local reactions to unexpected traffic fluctuations.

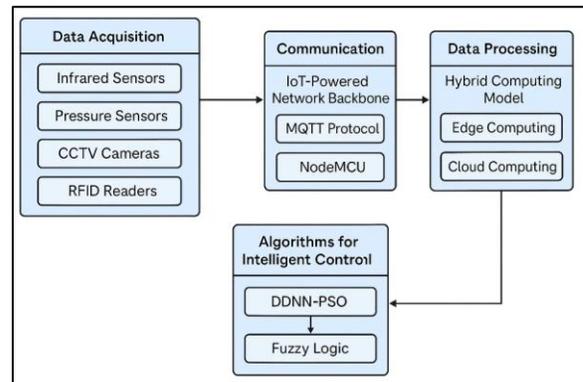
Cloud Computing for Insight: For advanced, long-term analysis, all the data is uploaded to a common cloud platform. It is here that our main algorithms, the DDNN-PSO and the Fuzzy Logic Inference System, are stored. The processing power of the cloud enables us to execute complicated predictive models, inspect historical traffic patterns, and generate high-level decisions that maximize flow through an entire city network, not just an individual intersection.

4.4 Intelligent Control Algorithms

The "smart" in our system derives from a two-pronged algorithmic strategy that unites advanced prediction with man-like reasoning.

The Predictive Engine: DDNN-PSO: The anticipation of congestion in our system is driven by a Dynamic Deep Neural Network (DDNN). The network is trained from both real-time and past user input to predict traffic patterns. We have also added a further layer of performance with a Particle Swarm Optimization (PSO) algorithm. PSO tweaks the internal parameters of the network to make sure that our anticipation is as precise as possible. The predictive element is crucial to proactive traffic management.

The Decision-Maker: Fuzzy Logic: The DDNN-PSO predictions are brought to reality through a Fuzzy Logic Controller. This controller works on a collection of logical "If-Then" rules, duplicating the manner in which a human driver would respond. That is, if high congestion is predicted, the fuzzy logic system calculates the exact time to lengthen the green light and smoothly adjusts to situations. This method guarantees that our system will not be static but dynamic, resulting in maximum traffic flow and less congestion.



V. CONCLUSION AND FUTURE WORK

5.1 Conclusion

This paper aimed to address the long-standing and intricate problem of urban traffic congestion, an issue that wastes resources, time, and environmental health for cities today. We've outlined an end-to-end Smart Traffic Congestion Control System based on the revolutionary capabilities of IoT-connected Wireless Sensor Networks (WSNs). Our system breaks free

from the constraints of conventional, fixed-time traffic management by combining real-time data acquisition with smart, adaptive algorithms.

At the center of our system is a multi-sensor data collection approach, in which infrared and pressure sensors are used to collect foundation vehicle information, CCTV cameras for visual context and crash detection, and importantly, RFID readers to prioritize urgent vehicles. This dense stream of data becomes the "eyes and ears" of the city's traffic network. This data is then effectively conveyed through an IoT-enabled backbone using NodeMCU hubs and light-weight MQTT protocol for data integrity as well as low latency.

Our groundbreaking hybrid computer model wisely balances pace and analytical depth. Edge computing manages real-time, localized response, enabling fast adaptation to abrupt traffic occurrences. In the meantime, cloud computing addresses more extensive, long-term analysis, providing shelter for our principal DDNN-PSO predictor algorithm and Fuzzy Logic decision-maker. The DDNN-PSO generates highly accurate traffic congestion predictions, predicting bottlenecks before they completely materialize, and the Fuzzy Logic controller then converts these predictions into adaptive, human-like traffic signal changes.

Through the integration of these cutting-edge elements – ranging from sensing and communication to predictive modelling and adaptive control – our system delivers a sound foundation for traffic flow optimisation. Combining Vehicle-to-Infrastructure (V2I) communication and dynamic congestion prediction, our system effectively translates into improved road safety, shorter travel times, and tangible progress towards more sustainable urban transportation. Though simulation and analytical observations confirm the superiority of this IoT-based method over traditional means, the actual promise is in the ability to form the future smart city transportation infrastructures.

5.2 Future Work

In the future, the journey towards completely intelligent city transport leaves us with several prospective avenues for further research and development from the basis laid down in the paper:

Extended Sensor Integration and Data Fusion: While our multi-sensor paradigm is strong, future studies can explore combining novel sensor technologies, such as LiDAR for enhanced vehicle location or acoustic sensors for real-time noise pollution detection. It would be essential to further develop data fusion techniques to effectively fuse these heterogeneous data sources to improve traffic congestion prediction accuracy and incident detection.

Reinforcement Learning for Dynamic Policy Adaptation: Our existing Fuzzy Logic controller is rule-based, but adaptive. A tremendous improvement would be to substitute or augment this with Reinforcement Learning (RL) algorithms. An RL agent would learn optimal traffic signal policies through trial and error either in the real world or in simulation, adjusting continuously to new traffic situations and even optimizing its control policies over long time frames.

Predictive Maintenance and Resilience: Besides managing near-term congestion, future research could touch on applying the collected data to predictive maintenance of road infrastructure and traffic equipment. By analyzing sensor health and traffic flow information, potential failure (e.g., traffic light system failure, road degradation) could be predicted, and preemptive action would be enabled, improving the overall resilience of the transportation system.

Integration with Urban Planning and Autonomous Vehicles: As the city grows, our system could also be integrated into broader paradigms of urban planning to regulate infrastructure development and public transportation planning. With the emergence of autonomous vehicles (AVs), the V2I communication capabilities could also be utilized to directly negotiate traffic with AVs, paving the way for a whole new set of paradigms for traffic control and movement optimization to previously unattained levels.

Cybersecurity and Privacy Solutions: Like any system that is IoT-capable, cybersecurity and privacy of the data are the central issues. Future work will include advanced encryption, secure communication protocols, and anonymization methodologies to protect sensitive traffic information and render the system immune to cyber attacks for achieving public trust in extensive adoption.

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