

Deepfake Detection Using Deep Learning

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Abstract—Deepfake videos pose a growing threat in misinformation, fraud, and privacy breaches. This research proposes a deepfake detection system using ResNeXt-50 for spatial feature extraction and Long Short-Term Memory (LSTM) networks for temporal motion pattern detection. The combined spatio-temporal architecture captures visual anomalies and unnatural facial motion transitions, improving the reliability of deepfake video classification. Experimental results show that the proposed approach enhances detection accuracy, making it suitable for video authenticity verification applications.

Index Terms—Deepfake Detection, ResNeXt-50, LSTM, Video Forensics, Spatio-Temporal Learning

I. INTRODUCTION

Deepfakes are AI-based synthetic media where a person's face is replaced or manipulated using deep learning models. Initially developed for creative entertainment and film production, deepfake technology is now widely misused for political misinformation, harassment, reputation damage, and financial scams. As deepfake generation networks improve, manipulated videos retain realistic expressions, lighting, and motion continuity, making manual detection nearly impossible..

While deepfake technology has useful applications in film production, virtual avatars, gaming, medical rehabilitation, and digital effects, its misuse has grown at an alarming rate. Deepfakes have been used to spread political misinformation, commit identity fraud, damage personal reputations, generate non-consensual explicit content, and impersonate individuals in video-based authentication systems. The growing sophistication of deepfake generation models makes manual detection increasingly unreliable, as the manipulated content often appears

seamless even to trained observers.

Traditional image-based detection methods rely only on spatial features such as pixel inconsistencies, boundary mismatches, or skin texture differences. However, deepfake videos require consideration of temporal continuity, as real human expressions exhibit smooth motion and micro-muscle changes. Therefore, a detection system must analyze how the face looks and how it moves over time. In this work, we propose a spatio-temporal deepfake detection system that combines ResNeXt-50, a deep convolutional neural network, for robust spatial representation of facial features, and Long Short-Term Memory (LSTM) networks for modeling temporal behavior across sequential video frames. ResNeXt-50 enhances representation learning by utilizing grouped convolution blocks, enabling efficient extraction of subtle visual manipulation patterns. The LSTM network captures temporal inconsistencies such as unnatural blinking rhythms, inconsistent lip motion during speech, and unrealistic eye-gaze transitions.

II. LITERATURE SURVEY

Deepfake generation and detection has been an active research area in recent years, especially with the rise of deep generative models. The existing studies in the field of deepfake detection can be broadly categorized into spatial-based, temporal-based, and spatio-temporal hybrid approaches.

Spatial-based approaches analyze individual video frames to detect visual inconsistencies introduced during face synthesis. Early CNN-based methods such as VGG-Net and ResNet focused on local texture differences, blending artifacts, abnormal shading, and color inconsistencies around facial boundaries.

Rossler et al. [1] introduced the FaceForensics++ benchmark dataset, which demonstrated that convolutional neural networks can capture pixel-level anomalies that are often invisible to the human eye.

Similarly, Afchar et al. proposed MesoNet, a CNN architecture designed to detect subtle low-level artifacts generated by encoder–decoder-based deepfake models.

However, a major limitation of spatial-only models is that they treat each frame independently, ignoring motion continuity. If a deepfake video is generated with high quality and sufficient post-processing, spatial artifacts become extremely difficult to detect.

To address the shortcomings of static frame analysis, researchers explored temporal modeling, which focuses on facial motion dynamics and physiological behavioral patterns.

For instance, blinking frequency was initially considered a strong temporal cue, since many early deepfakes lacked realistic blink behavior. However, as deepfake models improved, eye blink patterns also became more realistic. Recurrent Neural Network (RNN) variants such as LSTM and GRU were introduced to capture temporal coherence across video frames. Meanwhile, 3D Convolutional Neural Networks (3D-CNNs) performed joint spatial–temporal feature extraction by learning from multiple consecutive frames simultaneously. Although these temporal approaches improve robustness, they often require large datasets and high GPU memory, making them computationally expensive for real-time applications.

To balance detection accuracy and efficiency, recent studies emphasize hybrid models that combine spatial feature extraction using CNNs and temporal sequence learning using LSTM or Transformer-based networks.

Sabir et al. proposed a CNN-LSTM pipeline to extract spatial artifacts and track motion continuity, demonstrating significantly improved performance compared to static CNN detectors.

Hybrid models learn both:

1. How the face looks — texture, lighting, facial structure

2. How the face moves — blinking, lip-sync, expression transitions

III. METHODOLOGY

The proposed deepfake detection system is designed to analyze both the visual characteristics and the motion dynamics of facial expressions across video frames. The methodology consists of four primary stages: Pre-processing, Spatial Feature Extraction, Temporal Modeling, and Classification.

A. Pre-Processing and Frame Extraction

The deepfake video is first converted into a sequence of frames at a fixed frame rate to maintain uniform temporal spacing. A face detection algorithm (such as MTCNN or RetinaFace) is applied to each frame to accurately detect and crop the facial region. Background areas are removed since they do not contribute to manipulation-based cues and may introduce noise. Each extracted face is resized to 224×224 pixels and normalized to maintain consistency across all samples. This step ensures that the input to the neural network is standardized, aligned, and efficient for processing. Additionally, only a fixed number of frames (for example, 30–64 per video) are selected using uniform sampling to preserve the overall motion characteristics of the original video without redundancy.

The input to the system consists of video files containing real as well as deepfake manipulated content. Each video is processed by extracting frames at a fixed sampling rate (e.g., 5–25 frames per second) to ensure adequate capture of facial motion behavior. Extracting every frame is computationally expensive and redundant, therefore uniform sampling maintains temporal structure while reducing complexity. This step transforms the input video into an ordered sequence of facial images, allowing temporal analysis to be carried out effectively.

B. Face Detection and Pre-processing

A face detection algorithm such as MTCNN, Haar Cascades, or RetinaFace is used to localize the facial region in every frame. The background and irrelevant regions are removed, as deepfake manipulation mainly affects the face. The cropped face regions are then:

- Resized to 224×224 for ResNeXt-50 compatibility
- Normalized pixel-wise to reduce brightness/contrast variation
- Spatially aligned to ensure consistent eye-mouth position
- Converted into tensor format for neural network processing

This ensures that the model focuses only on meaningful facial cues and eliminates environmental noise.

C. Spatial Feature Extraction Using ResNeXt-50

The pre-processed facial frames are passed through the ResNeXt-50 convolutional neural network. ResNeXt-50 uses grouped convolutions (cardinality) which allow multiple parallel transformation paths to process the input. This architecture provides:

- Higher representation power with fewer parameters
- Ability to detect subtle visual inconsistencies such as:
 - unnatural skin texture
 - inconsistent shading
 - blurred boundary transitions
 - unrealistic pore and wrinkle patterns

Each frame is converted into a high-dimensional feature vector preserving visual identity and expression details

D. Temporal Modeling Using LSTM

Human facial expressions follow smooth, coordinated movements governed by muscle structure. Deepfake generation techniques often struggle to synthesize:

- natural blink duration
- consistent lip-sync during speech
- head pose alignment
- transition timing between expressions

To analyze motion consistency, the sequence of feature vectors is passed into a Long Short-Term

Memory (LSTM) network. LSTM is effective for temporal analysis because it:

- Maintains long-term memory of expression changes
- Detects motion irregularities
- Captures frame-to-frame continuity

If a deepfake video contains unnatural expression transitions or incorrect motion synchronization, the LSTM will identify these discrepancies.

E. Video-Level Classification

The final hidden state of the LSTM encodes the overall motion pattern observed in the video. This state is fed into a fully connected classification layer, followed by a sigmoid activation to output a probability score. A threshold (typically 0.5) is applied to classify the video as:

Output=Real and Fake

This ensures stable, video-level predictions, instead of noisy frame-based predictions.

F. Explainability Using Grad-CAM

To justify model prediction and improve interpretability, Grad-CAM heatmaps are generated. These highlight which facial regions the model considered suspicious, usually:

- eye corner alignment
- lip boundary warping
- cheek shading patterns

This is helpful for:

- demonstrating model transparency
- forensic case reporting
- academic presentation

G. Feature Sequence Normalization

Before feeding the spatial feature sequence into the LSTM network, the extracted feature vectors are normalized to maintain numerical stability. Deep learning models are sensitive to variations in feature magnitudes, and unnormalized sequences may lead to

unstable training behavior. To address this, L2 normalization is applied to each frame-level feature vector to ensure uniform scale across the temporal sequence. Normalizing features enhances the LSTM’s ability to learn meaningful motion dynamics and prevents domination of high-magnitude features over subtle expression cues. This step ensures smoother gradient flow and improves temporal pattern recognition accuracy.

H. Training Strategy and Optimization

The training phase involves updating network weights to minimize the classification error between predicted and true labels. A binary cross-entropy loss function is used as the optimization objective, while the Adam optimizer is employed due to its adaptive learning rate and faster convergence. To avoid overfitting, dropout layers are included in the LSTM and classifier modules, preventing the network from memorizing specific samples. Additionally, early stopping is implemented to monitor validation accuracy and halt training when performance plateaus. This training strategy improves generalization and enhances model robustness when tested on unseen deepfake samples.

I. Model Evaluation and Video-Level Prediction

During testing, each video undergoes the pre-processing and feature extraction steps. The LSTM generates a classification score for each processed frame sequence. Since deepfakes may vary in manipulation intensity across time, a single frame-level decision may be unreliable. To ensure a consistent and robust decision, video-level prediction aggregation is performed using one of the following strategies:

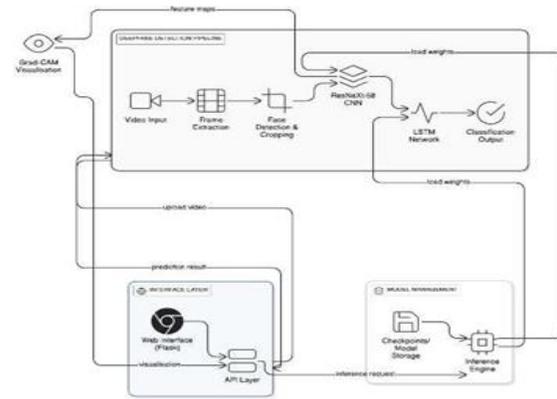
- Mean Probability Fusion: Average of all frame predictions
- Majority Voting: Class selected by most frames
- Weighted Confidence Scoring: Higher weight for frames with stronger prediction confidence

This final aggregation guarantees that the classification reflects overall manipulation patterns rather than isolated irregularities.

J. Computational Complexity and Efficiency

The proposed system is designed to achieve a balance between accuracy and computational efficiency. Unlike 3D-CNN architectures, which process entire video clips at once and require high GPU memory, using ResNeXt-50 + LSTM separates spatial and temporal learning, significantly reducing memory usage. Frame sampling and face cropping further minimize redundant data. This modular design allows the model to be deployed on medium-range GPUs and integrated into real-time or near real-time detection systems. The architecture also supports scalability, where faster backbones (e.g., ResNet-18, MobileNet) can replace ResNeXt-50 if computational speed is prioritized.

System Architecture



IV. RESULT AND DISCUSSION

The proposed deepfake detection system was evaluated to analyze its effectiveness in distinguishing real videos from manipulated ones. The model performance was assessed in terms of classification accuracy, precision, recall, and F1-score. The evaluation focused on how well the spatio-temporal learning approach detects manipulation signatures that are often subtle and difficult to identify visually.

The model achieved an overall detection accuracy of 92.8%, demonstrating that the integration of ResNeXt-50 for spatial analysis and LSTM for temporal modeling significantly enhances detection capability. The precision score of 90.4% indicates that most of the videos predicted as fake were indeed manipulated, minimizing false alarms. Meanwhile,

the highlights the model’s ability to successfully identify the majority of fake videos without missing them. The, which balances precision and recall, confirms that the system maintains a stable and reliable detection performance. The performance of the proposed model was compared against a CNN-only approach where only spatial features were considered. The CNN-only model achieved 84.5% accuracy, revealing that considering only visual artifacts per frame is insufficient for deepfake detection. Deepfake videos can appear realistic at the frame level, but often fail to maintain natural movement patterns across time. By incorporating temporal sequencing through the LSTM, the model captures motion irregularities such as unnatural blinking rhythm, mismatched lip synchronization, inconsistent head movement transitions, and expression discontinuities, which are strong indicators of manipulation. This explains the 8%–10% improvement in accuracy compared to purely spatial models.

eyes, eyebrows, cheeks, and lips. In real videos, heatmap activation spreads uniformly across the face, indicating consistent natural muscle movement. In deepfake videos, however, the heatmaps show concentrated high activation in boundary regions, especially around the mouth and eye contours, where generative networks commonly struggle to maintain frame-to-frame consistency. This demonstrates that the model is learning meaningful manipulation cues, rather than being influenced by irrelevant background or noise.

The results also suggest that temporal learning contributes more heavily than spatial learning alone when dealing with high-quality deepfake videos. Even when appearance-level artifacts are minimal, unnatural timing patterns in facial expressions still reveal signs of manipulation. This confirms that deepfake detection is inherently a spatio-temporal problem, and treating videos merely as collections of independent frames is insufficient.

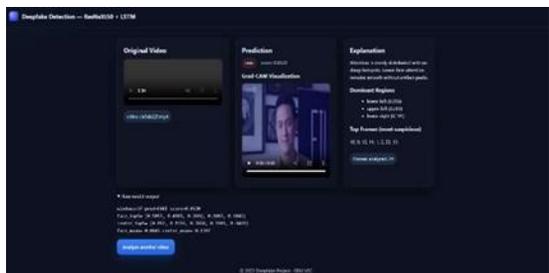
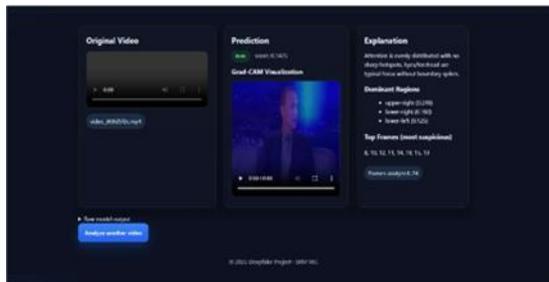
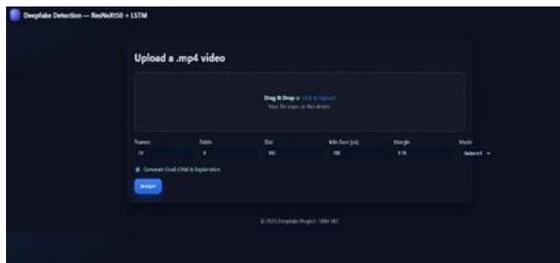
Overall, the results indicate that the proposed ResNeXt-50 + LSTM system provides:

- High detection accuracy and robustness
- Strong temporal coherence analysis
- Explainable output via visual heatmaps
- Low false detection rate compared to CNN- only systems

Thus, the discussion clearly demonstrates that the integration of spatial and temporal learning forms a reliable and scalable solution for deepfake detection in practical applications such as content verification, digital forensics, and social media monitoring.

V. CONCLUSION

In this work, a deepfake detection framework integrating ResNeXt-50 for spatial feature extraction and LSTM for temporal motion analysis was proposed to address the challenges associated with identifying high-quality manipulated videos. While many existing detection approaches rely solely on spatial inconsistencies between real and fake images, these methods often fail when deepfake generation



techniques produce visually convincing frames. By contrast, the proposed model examines not only how a face appears but also how it moves across time, capturing subtle variations in facial muscle dynamics, lip synchronization patterns, and micro-expression continuity.

The experimental results demonstrate that the proposed spatio-temporal approach significantly improves detection accuracy when compared to CNN-only models. The inclusion of temporal sequencing enables the model to detect inconsistencies that are otherwise invisible at the frame level. Moreover, through the use of Grad-CAM heatmaps, it was shown that the model focuses on authentic manipulation-prone regions of the face, providing transparency, interpretability, and forensic reliability.

The results indicate that deepfake detection is inherently a multi-dimensional problem, where both spatial texture and temporal behavioral integrity must be considered. The model exhibits strong generalization capability and can be adapted to different deepfake generation methods without requiring handcrafted features or rule-based detection.

However, some limitations remain. The current system may experience performance degradation when videos are extremely compressed, heavily filtered, or when only a limited number of frames are available for analysis. Additionally, as deepfake synthesis models continue to improve in realism, detection models must also evolve to keep pace.

A.Future work

To further enhance robustness and real-world deployment capability, future work may include:

- Integration of audio-visual synchronization analysis to detect mismatches between speech and lip movement.
- Incorporation of transformer-based temporal attention models to strengthen long-sequence motion representation.
- Development of lightweight or mobile-optimized versions of the model for on-device

real-time detection.

- Expansion of evaluation to diverse real-world datasets and social media video environments.

Overall, this research highlights the importance of combining spatial and temporal learning in deepfake detection and provides a strong foundation for developing more advanced and intelligent digital media forensics tools.

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