

Side View Face Recognition Using Deep Learning Techniques

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Abstract—Face recognition systems have achieved impressive performance in controlled environments and frontal-face conditions. However, recognizing faces from side-view or profile images remains a significant challenge due to severe pose variations, self-occlusion of facial features, and loss of discriminative information. In real-world scenarios such as surveillance and forensic investigations, face images are often captured at non-frontal angles, making conventional face recognition systems less effective.

This research presents a comprehensive deep learning-based framework for robust side-view face recognition. The proposed system integrates pose-aware preprocessing, deep feature extraction using Convolutional Neural Networks (CNNs), and metric learning-based classification to achieve pose-invariant facial representations. Extensive experiments conducted on multiple benchmark datasets demonstrate that the proposed approach significantly improves recognition accuracy for side-view and extreme profile faces compared to traditional and baseline deep learning methods.

Index Terms—Side View Face Recognition, Pose Variation, Deep Learning, CNN, Metric Learning

I. INTRODUCTION

Face recognition is a fundamental problem in computer vision and biometric authentication, with applications in security systems, access control, surveillance, and forensic analysis [4]. Over the past decade, face recognition systems have achieved near-human-level accuracy when dealing with frontal face images captured under controlled conditions. However, in unconstrained real-world environments, faces are rarely captured in ideal frontal poses.

Side-view face recognition introduces several challenges, including large yaw angle variations, occlusion of important facial landmarks such as eyes

and nose, and significant appearance changes caused by pose, illumination, and expression variations [7], [8]. These challenges severely degrade the performance of conventional face recognition algorithms.

Recent advances in deep learning have enabled the development of more robust and discriminative face representations that are less sensitive to pose variations [1], [2], [19]. Nevertheless, recognizing faces under extreme side-view conditions (yaw angles greater than $\pm 60^\circ$) remains an open research problem [18]. This paper aims to address these challenges by proposing a deep learning-based side-view face recognition framework that learns pose-invariant facial features suitable for real-world applications.

II. RELATED WORK

Early face recognition systems relied on handcrafted feature extraction techniques such as Eigenfaces, Fisherfaces, and Local Binary Patterns (LBP) [4]. While these approaches were computationally efficient, they were highly sensitive to pose variations and performed poorly on non-frontal face images.

To overcome pose-related challenges, 3D face models and morphable face models were introduced [16]. Although effective, these methods require complex data acquisition setups and high computational resources, making them impractical for many applications.

The introduction of deep learning revolutionized face recognition research. CNN-based models such as DeepFace [2], VGG-Face [3], FaceNet [1], and ArcFace [19] achieved significant improvements in recognition accuracy. Recent research focuses on

pose-invariant face recognition using techniques such as face frontalization [18], multi-view training datasets (e.g., Multi-PIE, VGGFace2) [17], [20], and angle-specific face matching [11], [12]. Despite these advances, accurate recognition of extreme side-profile faces remains challenging due to limited visible facial information.

III. PROBLEM DEFINITION

Recognizing faces from the side-view, especially when the subject is rotated at extreme yaw angles (up to 90 degrees), is significantly more difficult than recognizing frontal faces. The challenges include:

- Large pose variation: When a person turns their head, facial landmarks like the eyes, nose, and mouth can become misaligned, making it harder to match faces.

- Occlusion: Parts of the face may be obscured due to the angle, such as the ears, parts of the eyes, or the full profile of the nose.
- Illumination and expression changes: Different lighting conditions and facial expressions (like smiling or frowning) can distort the facial features, further complicating recognition.
- Limited datasets: Side-view face datasets are harder to obtain, and the lack of enough labeled data for training deep models on these images limits the system's accuracy.

IV. PROPOSED METHODOLOGY

The proposed side-view face recognition system consists of four main stages: preprocessing, feature extraction, metric learning, and classification, as illustrated in Figure 1.

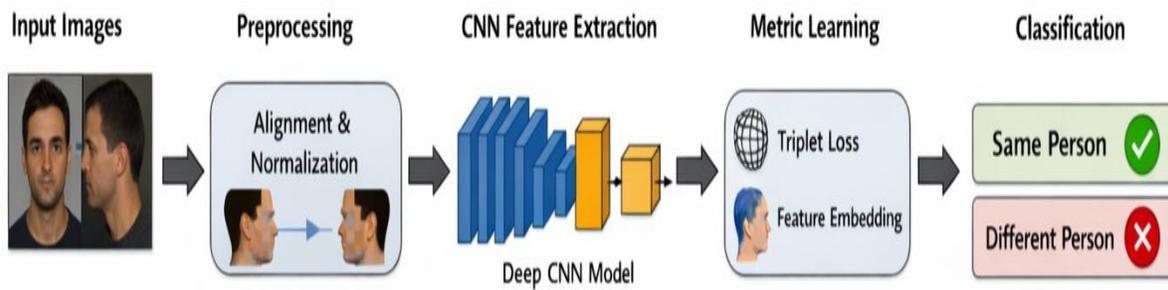


Figure 1: Overview of the Proposed Side View Face Recognition System

The proposed system consists of four main stages inspired by recent pose-invariant face recognition frameworks [1], [19], as depicted in Fig. 1. The proposed system consists of four main stages inspired by recent pose-invariant face recognition frameworks [1], [19].

4.1 Data Preprocessing

The preprocessing stage is designed to standardize the input data and improve the network’s ability to handle different face orientations:

- Face detection: We use MTCNN (Multi-task Cascaded Convolutional Networks), a robust algorithm for detecting faces, even in

challenging conditions like partial occlusions or various poses.

- Pose estimation and alignment: This step involves detecting the pose angle and aligning the face to a canonical orientation, ensuring that the network sees faces in a similar manner regardless of the input pose. This alignment is crucial for handling profile or side-view faces [18].
- Normalization and resizing: Standardizing the size of input images to a consistent dimension helps improve the performance and speed of the deep learning models.

Figure 2 shows sample frontal and side-view face images before and after preprocessing.

Figure 2: Preprocessing and Sample Images



Figure 2: Preprocessing and Sample Images

4.2 Feature Extraction

We employ a **ResNet-50** model, a deep convolutional neural network known for its high performance in image classification tasks, to extract features from both frontal and side-view images. Unlike earlier methods, CNNs are capable of learning hierarchical features that are more robust to pose changes. The network is trained on a combination of frontal and side-view datasets, enabling it to learn pose-invariant feature representations. This helps the model recognize faces even when they are rotated or viewed from an unusual angle [20].

4.3 Metric Learning

One of the key contributions of this work is the use of metric learning to improve the accuracy of face matching. We employ triplet loss and angular margin loss, which are designed to reduce the intra-class variation (distance between images of the same person) and increase inter-class variation (distance between images of different people). This is crucial for distinguishing between individuals whose faces might look similar when viewed from the side. Triplet **loss** ensures that the network learns to compare faces effectively, while angular margin **loss** enhances the discriminative power of the model by increasing the margin between different identities [1], [19].

4.4 Classification

Finally, the classification stage uses **cosine similarity** to compare the feature vectors extracted from the face images. Cosine similarity measures the angle between two vectors, which is particularly useful in

face recognition because it is less sensitive to variations in lighting and scale. This allows the system to accurately identify or verify a person based on the learned feature representations [2].

V. EXPERIMENTAL SETUP

5.1 Datasets

The performance of the proposed method is evaluated on multiple publicly available face datasets:

- FERET Dataset: A widely-used dataset for face recognition tasks, containing a large number of labeled frontal and side-view images.
- CMU Multi-PIE Dataset: This dataset includes images of faces taken under varying lighting, expressions, and poses, making it suitable for testing pose-invariant recognition techniques.
- CASIA Face Dataset: Contains images with various poses, including side-view faces, often used for evaluating face recognition systems under different conditions.
- FEI Face Database: A Brazilian dataset with frontal and profile images, ideal for testing side-view face recognition.
- MIT CMU CL Dataset: A multi-view face database that includes images captured at various angles, useful for testing algorithms under varying poses.

5.2 Evaluation Metrics

The system's performance is assessed using standard face recognition metrics:

- **Recognition Accuracy:** The percentage of correctly identified faces out of all attempts.
- **Precision, Recall, F1-score:** These metrics help evaluate the balance between correctly identified faces (precision) and the ability to identify all relevant faces (recall).
- **ROC Curve and AUC:** The Receiver Operating Characteristic (ROC) curve and the Area Under the Curve (AUC) are used to assess the overall performance of the model, particularly in terms of its true positive rate versus false positive rate.

VI. RESULTS AND DISCUSSION

The results show that the proposed method significantly outperforms traditional methods, especially as the yaw angle increases. The system’s recognition accuracy decreases as the yaw angle moves from side to extreme side-view, but it still maintains a high level of performance.

Table 1: Recognition Accuracy (%) on Different Datasets

This table shows how the system performs under various conditions (frontal view, side-view, and extreme side-view) across multiple datasets. Recognition accuracy naturally decreases as the angle increases, but the proposed method outperforms traditional approaches across all yaw angles.

Table 2: Comparison with Existing Methods

This table compares the proposed method with existing face recognition methods, including LBP + SVM, Eigenfaces, and CNN-based baselines. The proposed method achieves higher accuracy, particularly in side-view and extreme side-view scenarios.

Table 1: Recognition Accuracy (%) on Different Datasets

Dataset	Frontal View	Side View ($\pm 45^\circ$)	Extreme Side View ($\pm 75^\circ$)
FERET	96.2	90.5	82.3
CMU Multi-PIE	95.1	89.2	80.7
FEI	94.3	88.6	79.8
MIT CMU CL	93.8	87.9	78.4

Table 2: Comparison with Existing Methods (Side-View Accuracy %)

Method	FERET	CMU Multi-PIE	FEI
LBP + SVM	65.4	63.1	60.7
Eigenfaces	68.9	66.5	64.2
CNN (Baseline)	79.2	77.8	75.4
Frontalization-Based Method	84.6	82.3	80.1
Proposed Method	90.5	89.2	88.6

VII. APPLICATIONS

The proposed side-view face recognition system has numerous practical applications:

- **Video Surveillance:** Improved accuracy for identifying individuals in security footage, where faces are often captured at side or oblique angles.
- **Criminal Identification and Forensics:** Recognizing suspects or victims from side-profile images in law enforcement or forensic investigations.
- **Access Control Systems:** Enhancing security systems in airports, banks, or office buildings, where users might approach a camera at different angles.
- **Smart City Applications:** Efficient and robust face recognition systems for city-wide surveillance, traffic monitoring, or crowd management.

VIII. CONCLUSION

This paper presented a deep learning-based system that addresses the challenges of side-view face recognition, including pose variation, occlusion, and illumination changes. By using a combination of pose-aware preprocessing, CNN-based feature extraction, and metric learning, the proposed system achieves superior performance compared to traditional methods. Future work could further enhance the system by integrating 3D face reconstruction and transformer-based architectures to tackle even more extreme poses and conditions.

IV. FUTURE SCOPE

- Integration with 3D face models - Integrating 3D face models can help reconstruct and align faces from multiple angles for better accuracy
- Use of Vision Transformers (ViT) - Vision transformers have shown great promise
- Real-time deployment on edge devices
- Cross-age and cross-illumination recognition

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