

Li-Fi Data Transfer System Li-Fi Based Home Navigation

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Abstract— Li-Fi (Light Fidelity) is an emerging wireless communication technology that utilizes visible light for high-speed data transmission. Unlike conventional Wi-Fi, which operates on radio frequency (RF) signals, Li-Fi uses the visible light spectrum (400–800 Hz) to transmit binary data through rapid modulation of LED light sources. This project presents the design and implementation of a Li-Fi based home navigation system intended to assist visually impaired individuals in navigating indoor environments safely and independently.

Posed system is minimal. The prototype achieved a transmission range of approximately 7–8 meters under normal lighting conditions.

To address common Li-Fi limitations such as line-of-sight dependency and interference from other light sources, filters and adjustable LED positioning techniques are incorporated. The system demonstrates stable performance in both dark and moderately lit environments, provided a clear line of sight is maintained.

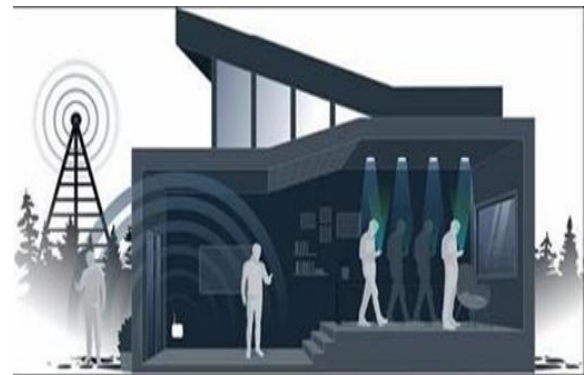
Index Terms— Li-Fi Technology, Visible Light Communication, Indoor Navigation System, Microcontroller-Based Implementation, Assistive Technology for Visually Impaired

I. INTRODUCTION

Indoor navigation remains a significant challenge for visually impaired individuals, particularly in unfamiliar environments such as homes, hospitals, educational institutions and office buildings. While traditional mobility aids like white canes and guide dogs assist in obstacle detection and movement, they do not provide precise information about the user's exact location within an indoor space. As a result, visually impaired individuals often face difficulties in identifying specific rooms or navigating independently in enclosed environments. With

advancements in wireless communication and smart technologies, there is a growing need for intelligent, secure, and cost-effective indoor navigation systems.

Light Fidelity (Li-Fi) is an emerging wireless communication technology that utilizes the visible light spectrum (400–800 Hz) to transmit data. Unlike conventional Wi-Fi systems that rely on radio frequency (RF) signals, Li-Fi transmits information by modulating the intensity of LED light at extremely high speeds, imperceptible to the human eye. This technology offers several advantages, including higher bandwidth, reduced electromagnetic interference, enhanced security, energy efficiency. Since light cannot penetrate walls, Li-Fi ensures secure point-to-point communication, making it particularly suitable for indoor applications.



This research proposes a Li-Fi based home navigation system designed specifically for visually impaired individuals. The system employs LED transmitters installed at room entrances and a receiver unit integrated into a walking stick. By decoding modulated light signals and converting them into audio feedback, the system provides real-time location information to users, thereby improving independence, safety, and overall quality of life.

II. RELATED WORK

Over the past decade, various indoor navigation and localization systems have been developed to assist visually impaired individuals using different wireless and sensing technologies. Early research primarily focused on Radio Frequency (RF)-based solutions such as Wi-Fi triangulation and Bluetooth beacons. These systems estimate the user's position by measuring signal strength from multiple access points. Although effective to some extent, RF-based systems suffer from signal interference, multipath fading, limited accuracy, and security vulnerabilities, particularly in complex indoor environments.

RFID-based indoor navigation systems have also been proposed, where RFID tags are installed at fixed locations and a reader detects nearby tags to determine position. While RFID provides reliable identification, its limited read range and infrastructure cost restrict large-scale deployment. Similarly, ultrasonic and infrared-based systems have been implemented for obstacle detection and localization, but they require additional hardware and are sensitive to environmental noise and obstructions.

Recent advancements in computer vision and deep learning have introduced camera-based navigation systems capable of object recognition and path detection. However, these systems demand high computational power, continuous lighting conditions, and may raise privacy concerns.

Visible Light Communication (VLC) has emerged as a promising alternative for indoor positioning. Researchers have demonstrated that LED-based Li-Fi systems can transmit location-specific information with high accuracy and minimal interference. However, many existing implementations rely on expensive photodiodes or complex signal processing techniques.

The proposed work builds upon VLC principles and introduces a cost-effective solution using Arduino microcontroller and LDR sensors, making the system practical, affordable, and easily deployable for real-world home navigation applications.

III. PROPOSED WORK

The proposed system presents a Li-Fi based indoor navigation solution specifically designed to assist visually impaired individuals in navigating enclosed

environments independently and safely. The system replaces conventional RF-based localization methods with Visible Light Communication (VLC), ensuring secure and interference-free transmission of location information. The architecture consists of two primary units: a transmitter unit installed at the entrance of each room and a receiver unit embedded within the user's walking stick. The transmitter unit comprises a high-brightness LED connected to a microcontroller such as arduino. Each LED is programmed to transmit a unique binary code corresponding to a specific room or location. Data transmission occurs by rapidly modulating the LED light intensity at a speed imperceptible to the human eye. This modulated visible light carries encoded location information continuously within the coverage area.

The receiver unit consists of a Light Dependent Resistor (LDR) arranged in a potential divider circuit, a Microcontroller and an audio output system. When the receiver enters the line-of-sight range of a transmitting LED, the LDR detects variations in light intensity and converts them into electrical signals. The microcontroller processes and decodes the received binary data, triggering a pre-recorded audio message that informs the user of their current location.

The system is designed to be cost-effective, energy-efficient, and easily deployable using existing LED lighting infrastructure. Basic filtering techniques are incorporated to reduce interference from ambient light. The modular design allows future expansion, including integration with IOT platforms, vibration feedback mechanisms, and advanced optical sensors for enhanced performance.

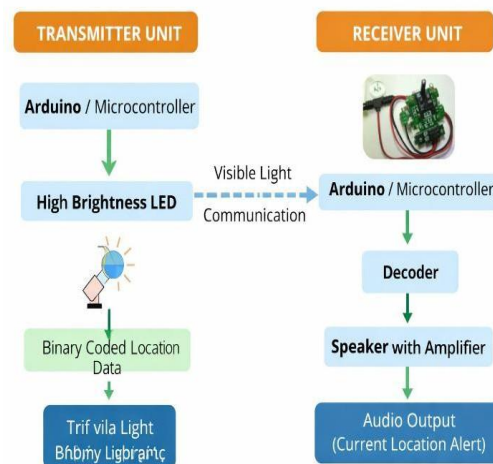


Fig. 1. Proposed work: indtigram



Fig. 2. Aurdino

IV. RESULT AND DISCUSSION

The proposed Li-Fi based home navigation system was experimentally implemented and tested under controlled in door condition stored value its performance, reliability, and practicality. The system consisted of multiple LED transmitters installed at different room entrances and a receiver unit embedded in a walking stick. Each LED transmitted a unique binary-coded signal corresponding to a specific location. The receiver unit, equipped with an LDR sensor, Arduino microcontroller, and speaker with amplifier, successfully detected and decoded the transmitted signals.

During testing, the system demonstrated reliable communication within a range of approximately 7–8 meters under normal indoor lighting conditions. When the receiver entered the line-of-sight (LOS) range of transmitting LED, the LDR detected variations in light intensity caused by high- speed modulation. The Arduino accurately decoded the binary sequence and triggered the corresponding pre- recorded audio message, such as “This is Bedroom” or “This is Bathroom.” The response time was observed to be less than one second, ensuring near real-time feedback for the user.



Fig. 3. Serial monitor result

The system maintained stable performance in moderately illuminated environments, provided that a clear LOS was maintained between the transmitter and receiver. Minor ambient light interference was observed; however, it did not significantly affect signal detection due to the use of threshold-based signal processing. The audio output was clear and audible, with the TIP120 transistor providing sufficient amplification for effective communication. One of the key advantages observed was enhanced security. Since visible light cannot penetrate walls, data transmission remained confined within a specific room, eliminating risks associated with RF-based signal leakage. Additionally, the use of existing LED lighting infrastructure makes the system energy-efficient and cost-effective.

However, certain limitations were identified. The system’s

Performance depends heavily on line-of-sight conditions, and obstacles blocking the light path temporarily interrupt communication. The transmission range is also limited compared to RF technologies. Despite these constraints, the experimental results confirm that the proposed Li-Fi navigation system is a feasible, reliable, and practical solution for indoor assistance, significantly improving mobility and independence for visually impaired individuals.

V. CONCLUSSION

The Li-Fi based home navigation system presented in this research offers a reliable, secure, and cost-effective solution to assist visually impaired individuals in indoor navigation. Traditional mobility aids such as white canes are primarily limited to obstacle detection and do not provide accurate location identification within enclosed environments. By integrating Visible Light Communication (VLC) technology with microcontroller-based processing, the proposed system addresses this limitation and enhances user independence and safety.

The system utilizes high-brightness LEDs as transmitters to send location-specific binary data through rapid light modulation, which is detected by an LDR –based receive embedded in a walking stick. The decoded data is converted into clear audio feedback, informing the user about their current position. Experimental results demonstrate that the system achieves reliable communication within a

range of 7–8 meters, with response times of less than one second. The use of visible light ensures enhanced security, as signals cannot penetrate walls, thereby prevent unauthorized access and reduce interference compared to RF-based systems.

One of the major advantages of the proposed system is its affordability and ease of deployment. Since most modern homes already use LED lighting infrastructure, minimal additional hardware is required for implementation. The modular architecture allows scalability and future expansion without significant redesign. Furthermore, the system consumes low power and operates efficiently under typical indoor lighting conditions.

Despite its advantages, certain limitations exist, including dependence on line-of-sight communication and limited transmission range. Ambient light interference may also affect performance if not properly filtered. These challenges provide opportunities for future improvements, such as replacing the LDR with a photodiode or solar cell for higher sensitivity, incorporating laser LEDs for extended range, and integrating vibration feedback mechanisms for multi-modal assistance. Additionally, IOT integration and smart home automation compatibility can further enhance system functionality.

Overall, the proposed Li-Fi based home navigation system represents a practical step toward intelligent assistive technology, promoting safer, more independent living for visually impaired individuals while contributing to the development of smart and inclusive indoor environments.

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